

Nov. 27/17

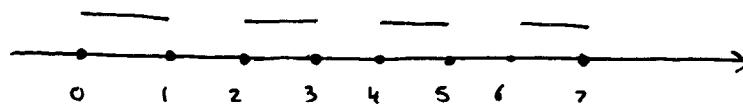
Applied Anal.

Let $f(t)$ be a particular function with period T ,

$$\mathcal{L}\{f(t)\} = \frac{1}{1-e^{-sT}} \int_0^T e^{-st} f(t) dt$$

$$\mathcal{L}\{E(t)\} = \frac{1}{s(1+e^{-sT})}$$

Where $\{E(t)\}$ is the square wave function



Example (A periodic impressed voltage)

The DE for the current $i(t)$ in a single-loop LR-series circuit

$$L \frac{di}{dt} + Ri = E(t)$$

Determine the current $i(t)$ when $i(0) = 0$

and $E(t)$ is the square wave function

Solution $L \mathcal{L}\left\{\frac{di}{dt}\right\} + R\{i\} = \mathcal{L}\{E(t)\}$

$$L(s I(s) - i(0)) + R I(s) = \frac{1}{s(1+e^{-s})}$$

$$(Ls + R) I(s) = \frac{1}{s(1+e^{-s})}$$

$$I(s) = \frac{1}{(Ls + R)(1+e^{-s})s}$$

$$i(t) = \mathcal{L}^{-1}\{I(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{s(Ls + R)} \cdot \frac{1}{1+e^{-s}}\right\}$$

$$= \mathcal{L}^{-1}\left\{\frac{1}{L} \cdot \frac{1}{s(s+R/L)} \cdot \frac{1}{1+e^{-s}}\right\}$$

$$= \frac{1}{L} \underbrace{\mathcal{L}^{-1}\left\{\frac{1}{s(s+R/L)} \cdot \frac{1}{1+e^{-s}}\right\}}$$

PARTIAL FRACTION

$$\frac{1}{(s)(s+R/L)} = \frac{A}{s} + \frac{B}{(s+R/L)} \Rightarrow \frac{(L/R)}{s} - \frac{(L/R)}{s+R/L}$$

$$i(t) = \frac{1}{L} \mathcal{L}^{-1}\left\{\left(\frac{L}{R} \cdot \frac{1}{s} - \frac{L}{R} \cdot \frac{1}{s+R/L}\right) \frac{1}{1+e^{-s}}\right\}$$

$$\Rightarrow \frac{1}{L} \cdot \frac{L}{R} \mathcal{L}^{-1}\left\{\left(\frac{1}{s} - \frac{1}{s+R/L}\right) \frac{1}{1+e^{-s}}\right\}$$

$$\Rightarrow \frac{1}{R} \mathcal{L}^{-1}\left\{\left(\frac{1}{s} - \frac{1}{s+R/L}\right) \left(\frac{1}{1+e^{-s}}\right)\right\} \quad \text{2nd (bring } e^{-s} \text{ up)}$$

(2)

geometric series

$$\frac{1}{1+x} = 1 - x + x^2 - x^3 \dots$$

$$x = e^{-s}, |e^{-s}| < 1$$

$$\rightarrow \frac{1}{1+e^{-s}} = 1 - e^{-s} + e^{-2s} - e^{-3s} + e^{-4s} \dots$$

$$i(t) = \frac{1}{R} \left[\left\{ \left(\frac{1}{s} - \frac{1}{s} e^{-s} + \frac{1}{s} e^{-2s} - \frac{1}{s} e^{-3s} + \dots \right) - \left(\frac{1}{s+R/L} - \frac{1}{s+R/L} e^{-s} + \frac{1}{s+R/L} e^{-2s} \dots \right) \right\} \right]$$

$$\Rightarrow \frac{1}{R} \left[(1 - u(t-1) + u(t-2) - u(t-3) \dots) - (e^{-R/L t} - e^{-R/L t} u(t-1) \dots + e^{-R/L t-2} u(t-2) - e^{-R/L t-3} u(t-3) \dots) \right]$$

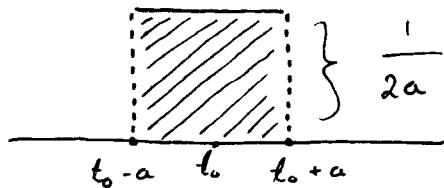
$$i(t) = \frac{1}{R} (1 - e^{-R/L t}) + \frac{1}{R} \sum_{n=1}^{\infty} (-1)^n (1 - e^{-R/L (t-n)}) u(t-n)$$

4.5 The Dirac Delta Function

Unit impulse $a > 0, t_0 > 0$

$$\delta_a(t-t_0) = \begin{cases} \infty, & 0 \leq t \leq t_0 - a \\ \frac{1}{2a}, & t_0 - a \leq t \leq t_0 + a \\ 0, & t \geq t_0 + a \end{cases}$$

$$\int_{-\infty}^{\infty} \delta_a(t-t_0) dt = 1$$



The Dirac Delta Function

$$\delta(t-t_0) = \lim_{a \rightarrow 0} \delta_a(t-t_0)$$

It is characterized by two properties

a) $\delta(t-t_0) = \begin{cases} \infty, & \text{if } t = t_0 \\ 0, & \text{if } t \neq 0 \end{cases}$

b) $\int_{-\infty}^{\infty} \delta(t-t_0) dt = 1$

Define the Laplace transform for $\delta(t-t_0)$

$$\mathcal{L}\{\delta(t-t_0)\} = \lim_{\alpha \rightarrow 0} \mathcal{L}\{\delta(t-t_0)\}$$

Thm. 4.5.1 For $t_0 > 0$

$$\mathcal{L}\{\delta(t-t_0)\} = e^{-st_0}$$

$$\text{Inverse } \mathcal{L}^{-1}\{e^{-st_0}\} = \delta(t-t_0)$$

Ex Solve the IVPs:

$$(a) y'' + y = 4\delta(t-2\pi), \quad y(0) = 1 \\ y'(0) = 0$$

$$(b) y'' + y = 4\delta(t-2\pi), \quad y(0) = 0 \\ y'(0) = 0$$

$$\underline{\text{Solution}} \quad (a) \quad \mathcal{L}\{y''\} + \mathcal{L}\{y\} = 4 \mathcal{L}\{\delta(t-2\pi)\}$$

$$(s^2 Y(s) - s^2 y(0) - y'(0)) + Y(s) = 4e^{-s \cdot 2\pi}$$

$$s^2 Y(s) - s + Y(s) = 4e^{-2\pi s}$$

$$(s^2+1)Y(s) = s + 4e^{-2\pi s}$$

$$Y(s) = \frac{s}{s^2+1} + 4e^{-2\pi s} \left(\frac{1}{s^2+1}\right)$$

$$y(t) = \mathcal{L}\left\{\frac{s}{s^2+1}\right\} + 4 \mathcal{L}^{-1}\left\{(e^{-2\pi s})\left(\frac{1}{s^2+1}\right)\right\}$$

$$= \cos t + 4 \sin(t-2\pi) u(t-2\pi)$$

$$\text{where } \mathcal{L}(t) = \mathcal{L}\left\{\frac{1}{s^2+1}\right\} = \frac{1}{s^2+1}$$

$$y = \cos t + 4 \sin(t-2\pi) u(t-2\pi)$$

$$y = \cos t + 4 \sin(t) u(t-2\pi)$$

$$(b) (s^2 Y(s) - s y(0) - y'(0)) + \mathcal{L}\{y\} = 4e^{-2\pi s}$$

$$(s^2+1)Y(s) = 4e^{-2\pi s}$$

$$Y(s) = \frac{4e^{-2\pi s}}{s^2+1}, \quad y = \mathcal{L}^{-1}\left\{\frac{4e^{-2\pi s}}{s^2+1}\right\}$$

$$= 4 \sin t u(t-2\pi)$$

Chapter 1: Basic Concepts, Terminology

Chapter 2: First Order Eq'n

(1) Separable equations

$$\frac{dy}{dx} = g(x)h(y)$$

$$\int \frac{1}{h(y)} dy = \int g(x) dx$$

(2) Linear Equations

$$a_1(x) \frac{dy}{dx} + a_0(x)y = g(x)$$

↓ Standard Form

$$\frac{dy}{dx} + P(x)y = f(x)$$

$$\frac{d}{dx} [e^{\int P(x) dx} \cdot y] = e^{\int P(x) dx} \cdot f(x)$$

(3) Exact Equations

$$M(x, y) dx + N(x, y) dy = 0$$

$$\text{is exact} (\Rightarrow) \frac{\delta M}{\delta y} = \frac{\delta N}{\delta x}$$

$$\left\{ \begin{array}{l} \frac{\delta f}{\delta x} = M \quad - (1) \quad \delta f(x, y) = 0 \\ \frac{\delta f}{\delta y} = N \quad - (2) \quad f(x, y) = C \end{array} \right.$$

2.7 - Linear Models

(1) Growth and Decay : $x(t)$ - amount of something

$\frac{dx}{dt}$ is proportional to the amount,

$$\text{i.e. } \frac{dx}{dt} = kx, \quad x(t_0) = x_0$$

half-life : the time t at which $x(t) = \frac{1}{2}x_0$

(2) Newton's Law of Cooling :

$T(t)$ - temp of object (or a body)

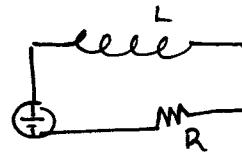
$$\frac{dT}{dt} = K(T - T_m)$$

→ the temperature of the medium

(3) Series Circuits :

$$L \frac{di}{dt} + R_i = E(t)$$

$$\left[\frac{dy}{dx} + P(x)y = f(x) \right]$$



Chapter 3 - higher order DE

3.1 - Linear equations : basic theory

$$a_3(x)y''' + a_2(x)y'' + a_1(x)y' + a_0(x)y = g(x)$$

(1) Solve the associated homo. eq'n. $\underbrace{\quad}$ (because = zero)

$$a_3(x)y''' + a_2(x)y'' + a_1(x)y' + a_0(x)y = 0$$

i.e. Find linearly indep. solutions

y_1, y_2, y_3 of the general solution

$$y = C_1 y_1 + C_2 y_2 + C_3 y_3$$

(2) Find a particular solution y_p for the non-homo.

(3) The general solution for the non-homo

$$y = C_1 y_1 + C_2 y_2 + C_3 y_3 + y_p$$

3.2 - Reduction of order

$$a_2(x)y'' + a_1(x)y' + a_0(x)y = 0$$

If we got a solution, $y_1 \neq 0$

How to find a second one

$y_2 = y_1 u(x)$ for some function

.... (long calculation)

Standard Form

$$y'' + P(x)y' + Q(x)y = 0$$

$$y_2 = y_1 \int \frac{e^{-\int P(x)dx}}{y_1^2} dx$$

3.4 Undetermined Coefficients

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Applied Anal.

$$ay'' + by' + cy = g(x)$$

To find a particular solution,

$y_p = g(x)$ by the type of functions $g(x)$ - See table.

If the assumed y_p is a solution of $ay'' + by' + cy = 0$

Then we assume a new particular solution Xy_p

Notes (a) a, b, c , are constants

$$x^2y'' + xy' + y = \sin x \quad (\times)$$

→ use variation of parameters

$$(b) 2y'' + 3y' - y = \frac{e^x}{(x+1)}$$

→ use the variation of parameters

3.5 Variation of Parameters

Standard Form $y'' + P(x)y' + Q(x)y = f(x)$

Let $y = C_1 y_1 + C_2 y_2$ be the general solution

of the associated homo. $y'' + P(x)y' + Q(x)y = 0$

A particular solution

$$y_p = y_1 U_1(x) + y_2 U_2(x) \quad \text{For two functions}$$

$$U_1(x), U_2(x)$$

$$U_1' = \frac{w_1}{w}, \quad U_2' = \frac{w_2}{w}$$

$$W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \quad W_1 = \begin{vmatrix} 0 & y_2 \\ f(x) & y_2' \end{vmatrix}$$

$$W_2 = \begin{vmatrix} y_1 & 0 \\ y_1' & f(x) \end{vmatrix}$$

3.6 Cauchy-Euler Equations

$$ax^2y'' + bx^2y' + cy = 0$$

$$\boxed{y = x^m} \quad \text{- Auxiliary Eq'n: } (am^2 + (b-a)m + c = 0)$$

$$\left\{ \begin{array}{l} \text{Remember : } ay'' + by' + cy = 0 \quad (y = e^{mx}) \\ ax^2y'' + bx^2y' + cy = 0 \quad (y = x^m) \end{array} \right\}$$

Ex. $\rightarrow x^2y'' - xy' + 3y = 0$

$$m^2 + (-1-1)m + 3$$

(I) $m_1 \neq m_2$ distinct real roots

$$y = C_1 x^{m_1} + C_2 x^{m_2}$$

(II) $m_1 = m_2$ repeated root

$$y = C_1 x^{m_1} + C_2 x^{m_2} \ln x$$

(III) $m_1 = \alpha + \beta i, m_2 = \alpha - \beta i$ are complex roots

$$y = C_1 x^\alpha \cos(\beta \ln x) + C_2 x^\alpha \sin(\beta \ln x)$$

Note: $x^2y'' - xy' + 3y = 2x^4e^x$

\rightarrow use variation of parameters

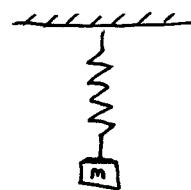
3.8 Linear Models

$$m \frac{d^2x}{dt^2} + \beta \frac{dx}{dt} + hx = f(t)$$

$$m = ? \quad \beta = ? \quad h = ? \quad f(t) = \dots$$

$$\text{initial conditions } x(0) = ?$$

$$x'(0) = ?$$



4. Laplace Transform

$$4.1 \quad \mathcal{L}\{f(t)\} = \int_0^\infty e^{-st} f(t) dt$$

$$4.2 \quad \mathcal{L}^{-1}\{F(s)\} = f(t)$$

$$\text{if } \mathcal{L}\{f(t)\} = F(s)$$

$$\mathcal{L}\{f'(t)\} = s \mathcal{L}\{f(t)\} - f(0)$$

$$\mathcal{L}\{f''(t)\} = s^2 \mathcal{L}\{f(t)\} - sf(0) - f'(0)$$

$$4.3 \quad / \quad \mathcal{L}\{e^{at} f(t)\} = \mathcal{L}\{f(t)\}|_{s \rightarrow s-a}$$

$$\mathcal{L}^{-1}\{F(s)|_{s \rightarrow s-a}\} = e^{at} \mathcal{L}^{-1}\{F(s)\}$$

$$2/ \quad \mathcal{L} \{ s(t-a) u(t-a) \} = e^{-as} \mathcal{L} \{ s(t) \}$$

$$\mathcal{L}^{-1} \{ e^{-as} F(s) \}$$

$$\mathcal{L}^{-1} \{ F(s) \} = f(t)$$

4.4

$$1/ \quad \mathcal{L} \{ t^n f(t) \} = (-1)^n \frac{d^n}{ds^n} \mathcal{L} \{ f(t) \}$$

$$2/ \quad \mathcal{L} \{ f * g(t) \} = \mathcal{L} \{ f(t) \} \cdot \mathcal{L} \{ g(t) \}$$

$$f * g(t) = \int_0^t f(y) g(t-y) dy$$

$$\mathcal{L}^{-1} \{ F(s) G(s) \} = \mathcal{L}^{-1} \{ F(s) \} * \mathcal{L}^{-1} \{ G(s) \}$$

$$3/ \quad \text{IF } f(t) \text{ is a periodic function with period } T,$$

$$\mathcal{L} \{ f(t) \} = \frac{1}{1-e^{-sT}} \int_0^T e^{-st} f(t) dt$$

4.5 The direct delta Function

$$\delta(t-t_0) = \lim_{\alpha \rightarrow 0} \delta_\alpha(t-t_0)$$

$$\mathcal{L} \{ \delta(t-t_0) \} = e^{-s t_0}$$

$$\mathcal{L}^{-1} \{ e^{-s t_0} \} = \delta(t-t_0)$$

3.3 - homogeneous linear DE w/ constant coeff.

$$ay'' + by' + cy = 0 \quad y = e^{mx}$$

where a, b, c are constants

Auxiliary eq'n:
$$am^2 + bm + c = 0$$

Case I : $m_1 \neq m_2$; real roots

$$C_1 e^{m_1 x} + C_2 e^{m_2 x}$$

Case II : repeated real root ; $m_1 = m_2$

$$y = C_1 e^{m_1 x} + C_2 e^{m_1 x} \cdot x$$

Case III : $m_1 = \alpha + \beta i \quad m_2 = \alpha - \beta i$

$$y = e^{\alpha x} \cos(\beta x) + e^{\alpha x} \sin(\beta x)$$

higher-order: $a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = 0$

$$\boxed{y = e^{mx}}$$

Auxiliary Equation = $a_n m^n + a_{n-1} m^{n-1} + \dots + a_1 m + a_0 = 0$

(I) m_1, m_2, \dots, m_n are distinct real roots

$$y = C_1 e^{m_1 x} + C_2 e^{m_2 x} + \dots + C_n e^{m_n x}$$

(II) m_1 is a real root, repeated k times

$$e^{m_1 x}, e^{m_1 x} \cdot x, \dots, e^{m_1 x} \cdot x^{k-1}$$

are k linearly independent solutions.

(III) IF $m_1 = \alpha + \beta i$ is complex root repeated k times

$$\text{then } m_2 = \alpha - \beta i \dots$$

$$e^{\alpha x} \cos(\beta x), x e^{\alpha x} \cos(\beta x), \dots, x^{k-1} e^{\alpha x} \cos(\beta x)$$

$$e^{\alpha x} \sin(\beta x), \dots, x^{k-1} e^{\alpha x} \sin(\beta x)$$

are $2k$ linearly indep. solutions.