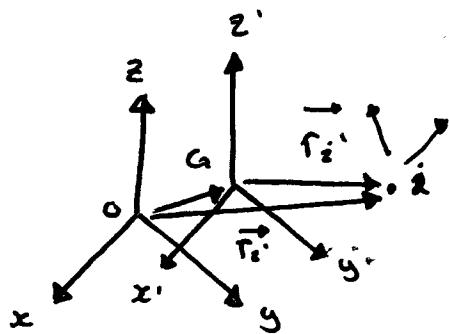


(1)

OCT. 24 / 17

DYNAMICS II



$$\vec{f}_i = \vec{T}_G + \vec{f}_{i,G}$$

$$\vec{v}_i = \vec{v}_G + \vec{v}_{i,G}$$

$$\begin{aligned}\vec{H}_G &= \sum \vec{f}_i \times m_i \vec{v}_i \\ &= \sum \vec{f}_i \times (m_i \vec{v}_i - m_i \vec{v}_G)\end{aligned}$$

$$\Rightarrow \vec{H}_G = \sum \vec{f}_i \times$$

$$= \sum \vec{f}_i \times m_i v_i - (\sum m_i \vec{f}_i) \times \vec{v}_G$$

$$H_G = \sum \vec{f}_i \times m_i \vec{v}_i$$

$$\begin{aligned}\frac{d}{dx} \vec{H}_G &= \frac{d}{dt} \sum \vec{f}_i \times m_i \vec{v}_i \\ &= \sum \vec{f}_i \times m_i \vec{v}_i + \sum \vec{f}_i \times m_i \vec{v}_i\end{aligned}$$

$$\dot{\vec{H}}_G = \sum \vec{M}_G$$

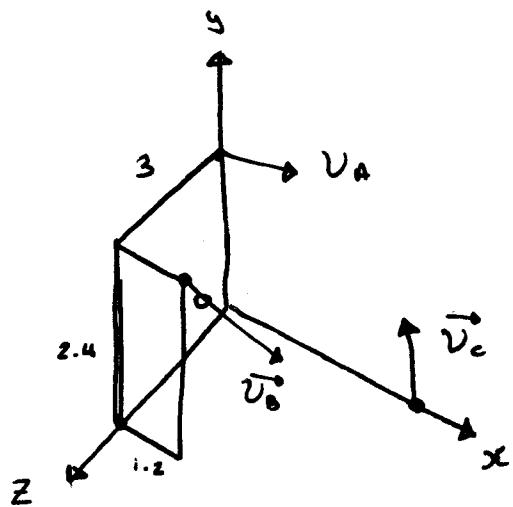
#### 14.6 Conservation of momentum

If no external forces act on the particles of the system, then the linear momentum and angular momentum about the fixed point are conserved.

$$\sum \vec{F} = \frac{d\vec{L}}{dt} \Rightarrow \boxed{\vec{L} = \text{const}}$$

$$\sum \vec{m} = \frac{d\vec{H}}{dt} = \boxed{\vec{H} = \text{const}}$$

(2)



$$M_A = 3 \text{ kg}$$

$$M_B = 2 \text{ kg}$$

$$M_C = 9 \text{ kg}$$

$$\vec{v}_A = 4\hat{i} + 2\hat{j} + 2\hat{k}$$

$$\vec{v}_B = 4\hat{i} + 3\hat{j} \dots$$

...

$$3 + 2 + 4 = 9$$

Find  $\vec{v}_G$ :

Solution

$$m = M_A + M_B + M_C$$

$$f_G = \frac{M_f_A + M_f_B + M_f_C}{m}$$

$$= (3)(3\hat{j}) + (2)(1.2\hat{i} + 2.4\hat{j} + 3\hat{k}) + (9) \dots$$

= ...

$$\vec{f}_A' = \vec{f}_A - \vec{f}_G, \quad \vec{f}_B' = \vec{f}_B - \vec{f}_G, \quad \vec{f}_C' = \vec{f}_C - \vec{f}_G$$

$$\vec{H}_G' = \sum \vec{f}_i' \times m_i \vec{v}_i$$

$$(\vec{v}_G = \frac{M_A \vec{v}_A + M_B \vec{v}_B + M_C \vec{v}_C}{m})$$

$$\vec{v}_G = 1.3333\hat{i} + 3.1111\hat{j} + 1.5556\hat{k}$$

$$H_G' = \vec{f}_A' \times M_A (\vec{v}_A - \vec{v}_G)$$

$$+ \vec{f}_B' \times M_B (\vec{v}_B - \vec{v}_G)$$

$$+ \vec{f}_C' \times M_C (\vec{v}_C - \vec{v}_G)$$

$$= -28\hat{i} + 13.33\hat{j} - 24.267\hat{k}$$

$$\vec{H}_G' = \sum \vec{f}_i' \times m_i \vec{v}_i$$

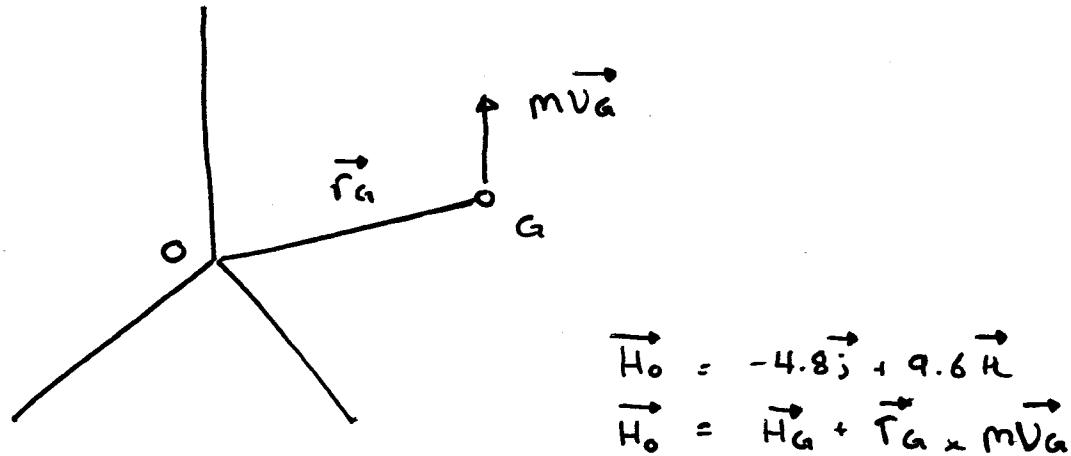
$$= \vec{f}_A' \times M_A \vec{v}_A + \vec{f}_B' \times M_B \vec{v}_B + \vec{f}_C' \times M_C \vec{v}_B$$

$$= 12.8\hat{i} + 3.20\hat{j} - 28.8\hat{k}$$

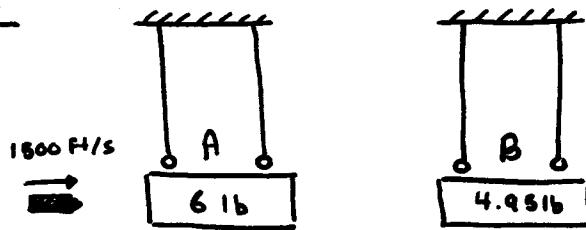
$$- 14\hat{i} + 18.6667\hat{j} - 10.9333\hat{k}$$

$$= 1.6\hat{i} - 8.5333\hat{j} + 15.4667\hat{k}$$

$$= -2.8\hat{i} + 13.33\hat{j} - 24.267\hat{k}$$



### Example



Blocks A and B start moving with velocities of 5 ft/s and 9 ft/s.

- Find the weight of the bullet
- Find the velocity of the bullet when it travels from A to B

Solution: The bullet, A, B as a system, there is no external horizontal forces, conservation of the linear momentum of the system in the horizontal direction.

before impact:  $V_o = 1500 \text{ ft/s}$

$$V_A = V_B = 0$$

$$L_o = mV_o + m_A V_A + m_B V_B = 1500m$$

(4)

After the bullet embedded in block B:

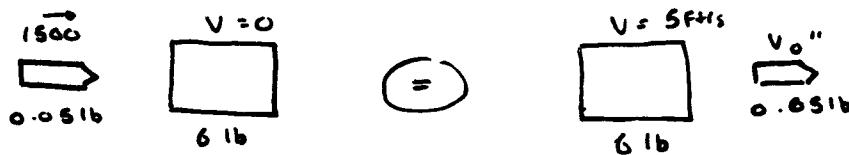
$$V_A' = 5 \text{ ft/s} \quad V_B' = V_0' = 9 \text{ ft/s}$$

$$L_0' = m V_0' + M_A V_A' + M_B V_B'$$

$$L_0' = (m)(a) + (6/32.2)(5) + (4.95/32.2)(9) = 1500$$

$$L_0 = L_0' \quad \hookrightarrow W = mg = 0.05 \text{ lb}$$

b) The bullet and block A as a system,  
conservation of linear momentum of  
the system.



$$\left(\frac{0.05}{32.2}\right)(1500) + 0 = \left(\frac{6}{32.2}\right)(5) + \left(\frac{0.05}{32.2}\right)V_0''$$

$$V_0'' = 900 \text{ ft/s}$$

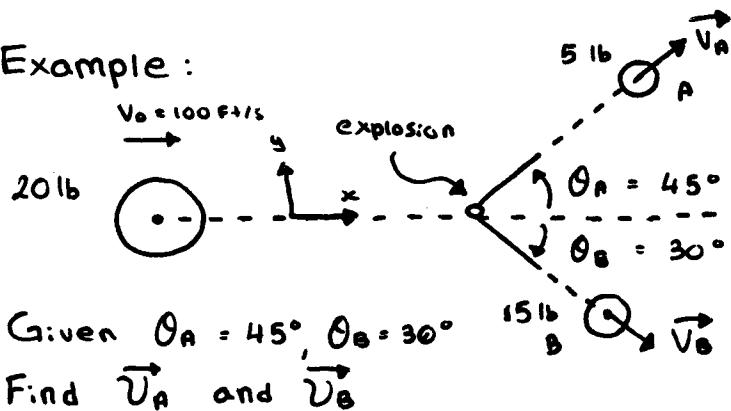

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if  $\Delta t = 0.005 \text{ s}$   $\vec{F}$ ?

using Bullet and B



Example :



Given  $\theta_A = 45^\circ$ ,  $\theta_B = 30^\circ$   
Find  $\vec{V}_A$  and  $\vec{V}_B$

$$\text{Solution : } (m_A + m_B) \vec{V}_0 = m_A \vec{V}_A + m_B \vec{V}_B$$

$$x : (m_A + m_B) V_0 = m_A V_A \cos \theta_A + m_B V_B \cos \theta_B$$

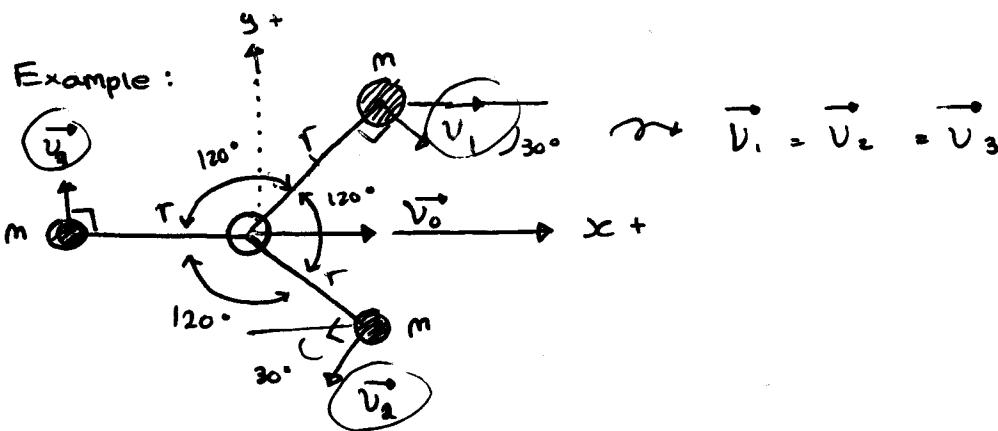
$$y : 0 = m_A V_A \sin \theta_A + m_B V_B \sin \theta_B$$

$$\Rightarrow V_A = 207 \text{ ft/s}$$

$$V_B = 97.6 \text{ ft/s}$$

Oct. 25 / 17

## DYNAMICS II



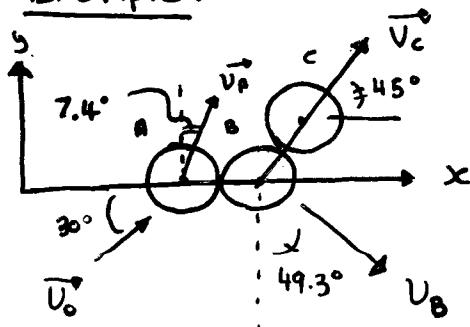
- the linear momentum of the system is in the positive x-direction; correct, ( $\vec{V}_0 > \theta$ )
- the angular momentum of the system is in the positive y-direction; x-direction
- the angular momentum of the system about G is zero;  $x = 3mV_r T \vec{n}$
- the linear momentum of the system is zero: False

$$M + (\vec{V}_1 + \vec{V}_0) + M(\vec{V}_2 + \vec{V}_0) + M(\vec{V}_3 + \vec{V}_0) = \dots$$

$$\dots 3m\vec{V}_0 + \underbrace{M(\vec{V}_1 + \vec{V}_2 + \vec{V}_3)}_{\zeta = 0} \neq 0$$

↑

If  $V_0 \neq 0$ , this is not true

Example:Given  $\vec{V}_0 = 12 \text{ ft/s}$  $\vec{V}_C = 6.29 \text{ ft/s}$ Find  $\vec{V}_A$  and  $\vec{V}_B$

Solution : No external impulsive forces in  
the horizontal direction

=> Conservation of linear momentum of  
the system.

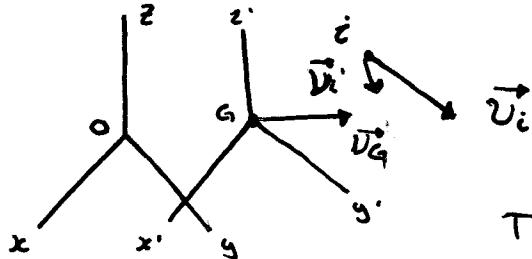
$$\Rightarrow M \vec{V}_o + \vec{0} + \vec{0} = M \vec{V}_A + M \vec{V}_B + M \vec{V}_C$$

$$x: M \vec{V}_o \cos(30^\circ) = M \vec{V}_A \sin(7.4^\circ) + M \vec{V}_B (\sin 49.3^\circ) + M \vec{V}_C (\cos 45^\circ)$$

$$y: M \vec{V}_o \sin(30^\circ) = M \vec{V}_A \cos(7.4^\circ) + M \vec{V}_B (\cos 49.3^\circ) + M \vec{V}_C (\sin 45^\circ)$$

$$\text{Mass is constant: } V_A = 6.05 \text{ ft/s}$$

$$(\text{all have same mass}) \quad V_B = 6.81 \text{ ft/s}$$

14.7 Kinetic Energy

$$T_i = \frac{1}{2} m_i v_i^2 \\ = \frac{1}{2} m_i \vec{v}_i \cdot \vec{v}_i$$

$$\vec{v}_i = \vec{v}_i' + \vec{v}_G'$$

$$T_i = \frac{1}{2} m_i (\vec{v}_i' + \vec{v}_G') \cdot (\vec{v}_i' + \vec{v}_G')$$

$$\therefore T = \sum_{i=1}^n T_i = \sum \frac{1}{2} m_i \vec{v}_i' \cdot \vec{v}_i' \\ + \sum \frac{1}{2} m_i \vec{v}_G' \cdot \vec{v}_G' \\ + \sum m_i \vec{v}_i' \cdot \vec{v}_G'$$

$$= \frac{1}{2} \sum M_i v_i^2 + \frac{1}{2} (\sum m_i) v_G^2 + \cancel{(\sum m_i v_i) \cdot v_G}$$

$$T = \frac{1}{2} \sum m_i v_i^2 + \frac{1}{2} m v_G^2$$

$$\sum \dot{\vec{F}}_i = \dot{\vec{L}}$$

$$\sum \vec{M}_o = \dot{\vec{H}}_o$$

14.8 Work-Energy Principle

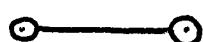
Particle  $\underline{i}$  :

$$T_1^{(i)} + \sum U_{1 \rightarrow 2} = T_2^{(i)}$$

System :

$$\sum T_1^{(i)} + \sum U_{1 \rightarrow 2}^{(i)} = \sum T_2^{(i)} \quad \text{general case}$$

$$\Rightarrow T_1 + U_{1 \rightarrow 2} = T_2 \quad (\text{work energy principle})$$



If the forces acting on the particles are conservative :

$$T_1 + V_1 = T_2 + V_2 \quad (\text{conservation of energy})$$

↳ special case

14.9 Principle of Impulse and Momentum

$$\sum \dot{\vec{F}}_i = \dot{\vec{L}}$$

$$\int_{t_1}^{t_2} \sum \dot{\vec{F}}_i dt = \int_{t_1}^{t_2} \dot{\vec{L}} dt = \vec{L}_2 - \vec{L}_1$$

↑  
impulse

2y

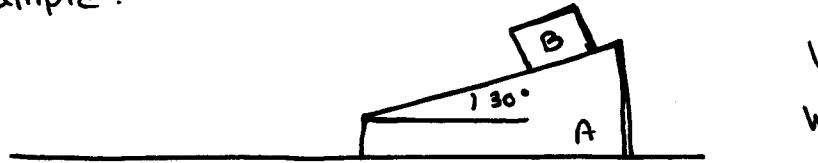
$$\Rightarrow \vec{L}_i + \sum \int_{t_1}^{t_2} \vec{F}_i dt = \vec{L}_2$$

$$\sum \vec{M}_o = \vec{H}_o$$

$$\int_{t_1}^{t_2} \sum \vec{M}_o dt = \int_{t_1}^{t_2} \vec{H}_o dt = \vec{H}_2 - \vec{H}_1$$

$$\Rightarrow \vec{H}_1 + \sum \int_{t_1}^{t_2} \vec{M}_o dt = \vec{H}_2$$

Example:



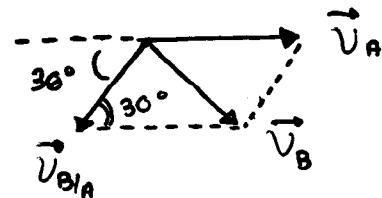
$$W_A = 25 \text{ lb}$$

$$W_B = 15 \text{ lb}$$

- Determine : a) the velocity of B relative to A after it has slid 3 ft down the machined surface of the wedge from rest.  
 b) the corresponding velocity of A

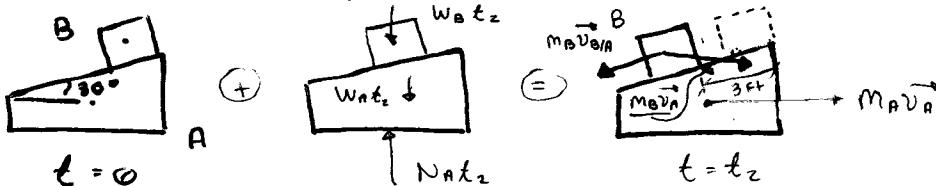
Solution : Relative velocity analysis :

$$\vec{V}_B = (\vec{V}_{B/A}) + (\vec{V}_A)$$



$$V_B^2 = V_A^2 + V_{B/A}^2 - 2V_A V_{B/A} \cos(30^\circ) \quad \text{--- (1)}$$

Principle of impulse and momentum :



(3)

$$Σ: \emptyset + \emptyset = m_A v_A + m_B v_B - m_B v_{B/A} \cos 30^\circ \quad (2)$$

$$\Rightarrow v_A = \frac{m_B}{m_A + m_B} v_{B/A} \cos(30^\circ) = 0.32476 v_{B/A} \quad (3)$$

$$(3) \rightarrow (1) : v_B^2 = 0.54297 v_{B/A}^2 \quad (4)$$

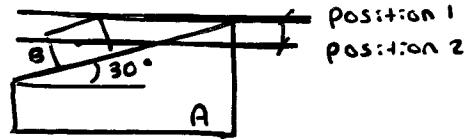
Conservation of Energy :

$$T_1 + V_1 = T_2 + V_2$$

$$T_1 = \emptyset, V_1 = \emptyset$$

$$T_2 = \frac{1}{2} m_A v_A^2 + \frac{1}{2} m_B v_B^2$$

$$V_2 = -W_B ds \sin 30^\circ$$



$$\emptyset + \emptyset = \frac{1}{2} m_A v_A^2 + \frac{1}{2} m_B v_B^2 - W_B ds \sin 30^\circ$$

$$(3)(4) \rightarrow (5) :$$

$$\left(\frac{1}{2}\right)\left(\frac{25}{32.2}\right)(0.32476 v_{B/A})^2 + \left(\frac{1}{2}\right)\left(\frac{15}{32.2}\right)(0.5429 v_{B/A}^2) = 15(3) \sin 30^\circ$$

$$\Rightarrow v_{B/A} = 11.59 \text{ ft/s}$$

$$\therefore \overrightarrow{v}_{B/A} = 11.59 \text{ ft/s} \quad \overbrace{\text{---}}^{30^\circ}$$

$$(3): v_A = 0.32476 v_{B/A} = 3.76 \text{ ft/s}$$

$$\therefore \overrightarrow{v}_A = 3.76 \text{ ft/s} \quad \overbrace{\text{---}}^{\text{---}}$$