

### 3 - Composites

A composite area, volume, or line is one composed of a combination of simple parts. You can easily determine its centroid if you know the centroids of its parts.

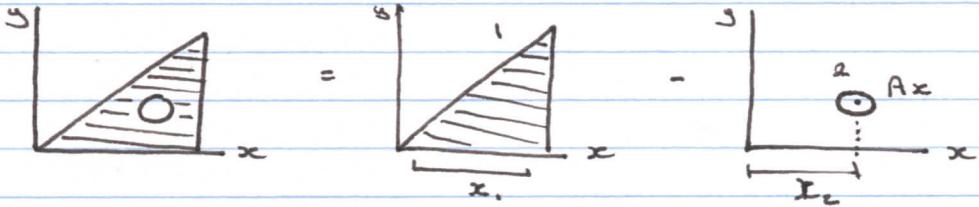
#### 3.1 - Composite Areas

The x-coordinate of the centroid of a composite area is:

$$\bar{x} = \frac{\bar{x}_1 A_1 + \bar{x}_2 A_2 + \dots \bar{x}_n A_n \dots}{A_1 + A_2 + \dots + A_n} \Rightarrow \frac{\sum_i \bar{x}_i A_i}{\sum A_i}$$

and y:  $\bar{y} = \frac{\bar{y}_1 A_1 + \bar{y}_2 A_2 + \dots \bar{y}_n A_n \dots}{A_1 + A_2 + \dots + A_n} \Rightarrow \frac{\sum_i \bar{y}_i A_i}{\sum A_i}$

The terms corresponding to a cutout (hole) in these equations will be negative.



#### 3.2 - Composite Volumes

$$\bar{x} = \frac{\sum_i \bar{x}_i V_i}{\sum V_i}; \quad \bar{y} = \frac{\sum_i \bar{y}_i V_i}{\sum V_i}; \quad \bar{z} = \frac{\sum_i \bar{z}_i V_i}{\sum V_i}$$

#### 3.3 - Composite Lines

$$\bar{x} = \frac{\sum_i \bar{x}_i L_i}{\sum_i L_i}; \quad \bar{y} = \frac{\sum_i \bar{y}_i L_i}{\sum_i L_i}; \quad \bar{z} = \frac{\sum_i \bar{z}_i L_i}{\sum_i V_i}$$

#### 3.4 Centers of Mass of Composite Objects

$$\bar{x} = \frac{\sum_i \bar{x}_i m_i}{\sum m_i}; \quad \bar{y} = \frac{\sum_i \bar{y}_i A_i}{\sum m_i}; \quad \bar{z} = \frac{\sum_i \bar{z}_i m_i}{\sum m_i}$$

and

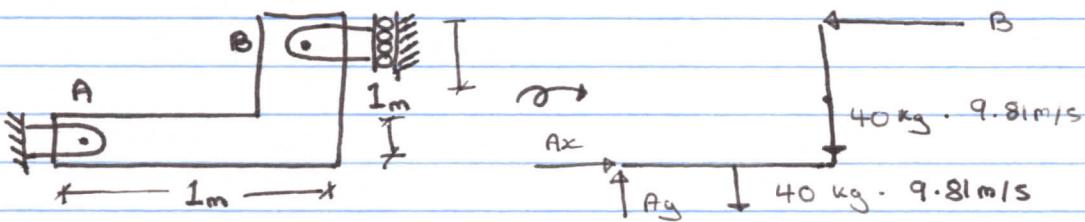
$$\bar{x} = \frac{\sum_i \bar{x}_i w_i}{\sum w_i}; \quad \bar{y} = \frac{\sum_i \bar{y}_i w_i}{\sum w_i}; \quad \bar{z} = \frac{\sum_i \bar{z}_i w_i}{\sum w_i}$$

(2)

When you know the masses or weights and the centers of mass or weights of the parts of a composite object, you can determine its center of mass

EXAMPLE:

The mass of a homogeneous slender bar is 80 kg, what are the reactions at A and B?



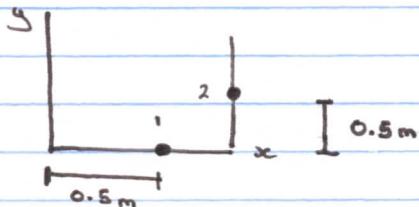
(essentially weight distribution  
by method of sections)

$$\begin{aligned}\sum F_x &= A_x - B \\ \sum F_y &= A_y - 2(40 \cdot 9.81) = 0 \\ A_y &= 784.8 \text{ N}\end{aligned}$$

$$\begin{aligned}\sum M_A &= (1)B - (1)(40)(9.81) - (0.5)(40)(9.81) \\ B &= 588.6 \text{ N} ; A_x = 588.6 \text{ N}\end{aligned}$$

Second Method: We can treat the centreline of the bar as a composite line composed of two straight segments, the coordinate of the centroid of the composite line is:

Note: Figure 5.8A and B show Centroids of common shapes of areas.



$$\bar{x} = \frac{\bar{x}_1 L_1 + \bar{x}_2 L_2}{L_1 + L_2} = \frac{(0.5)(1) + (1)(1)}{(2)}$$

$$\bar{y} = \frac{\bar{y}_1 \bar{x}_1 + \bar{y}_2 \bar{x}_2}{L_1 + L_2} = \frac{(0)(1) + (0.5)(1)}{(2)}$$

$$\bar{x} = 0.75\text{m}$$

$$\bar{y} = 0.25\text{m}$$

In the Free-body diagram we place the weight of the bar at its center of mass. From the equilibrium equations

$$\sum F_x = A_x - B = 0$$

$$\sum F_y = A_y - (80)(9.81) = 0$$

$$\sum M_A = (1)B - (0.85)(80)(9.81) = 0$$

Solving, we get  $A_x = 588.6 \text{ N}$ ;  $A_y = 784.8 \text{ N}$   
 $B = 588.6 \text{ N}$

### Theorems of Pappus-Guldinus

Theorem I: The area of a surface of revolution is equal to the length of the generating curve times the distance traveled by the centroid of the curve while the surface is being generated.

Theorem II: The volume of a body of revolution is equal to the generating area times the distance traveled by the centroid of the area while the body is being generated.

### Moments of Inertia

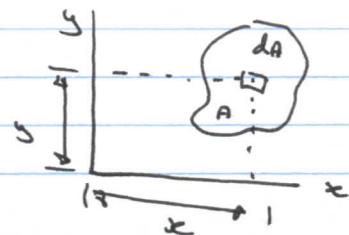
#### 1. Definition

The moment of inertia of an area are integrals similar in form to those used to determine the centroid of an area. We define four moments of inertia of an area  $A$  in the  $x-y$  plane:

##### 1.1 - Moment of Inertia about the $x$ -axis

$$I_x = \int_A y^2 dA$$

where  $y$  is the  $y$ -coordinate of the differential element of area  $dA$ . This moment of inertia is sometimes expressed in terms of the radius of gyration about  $x$ -axis,  $k_x$  defined by  $I_x = k_x^2 A$



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## Moments of Inertia

1.2 - Moment of Inertia about the y-axis

$$I_y = \int_A x^2 dA$$

$$I_x = \int_A y^2 dA$$

1.3 - Product of Inertia

$$I_{xy} = \int_A xy dA$$

1.4 - Polar moment of Inertia

$$J_o = \int_A r^2 dA$$

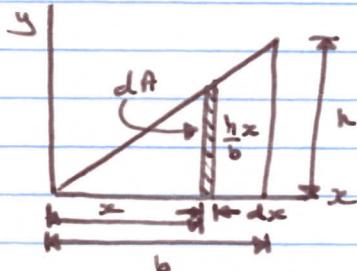
where  $r$  is radial distance from the origin  $O$  to  $dA$  the radius of gyration about  $O$ ,  $K_o$  is defined as:  $J_o = K_o^2 A$

The polar moment of inertia is equal to the sum of the moment of inertia about the x and y axes.

$$J_o = \int_A r^2 dA = \int_A (x^2 + y^2) dA = I_x + I_y$$

$$\text{and } K_o^2 = K_x^2 + K_y^2$$

- Determine the moments of inertia and radius of gyration of the triangular area shown:



Let  $dA$  be the vertical strip

↪ its height is  $\frac{h}{b} x$

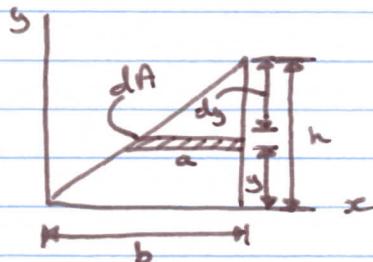
$$dA = \frac{h}{b} x \cdot dx$$

$$I_y = \int_A x^2 dA = \int_a^b x^2 \frac{h}{b} x dx$$

$$\begin{aligned} \text{The radius of gyration } &= \frac{h}{b} \left[ \frac{x^4}{4} \right]_0^b = \frac{1}{4} hb^3 \\ K_y \text{ is } I_y &= K_y^2 A \end{aligned}$$

$$K_y = \sqrt{\frac{I_y}{A}} = \sqrt{\frac{\frac{1}{4}hb^3}{\frac{1}{2}bh}} = \left( \frac{1}{\sqrt{2}} b \right)$$

- Determine the moment of inertia about the  $x$ -axis. Let  $dA$  be the horizontal strip.



Let  $dA$  be the horizontal strip

$$dA = (1 - y/h) b \, dy$$

$$I_{x_0} = \int_A y^2 dA = \int_a^b y^2 (1 - y/h) b \, dy$$

$$\Rightarrow b \left[ \frac{y^3}{3} - \frac{y^4}{4h} \right]_a^b$$

$$I_{x_0} = b \left( \frac{h^3}{3} - \frac{h^4}{4} \right) = \frac{1}{12} b h^3$$

$$\text{and } M_{x_0} = \sqrt{\frac{I_{x_0}}{A}} = \sqrt{\frac{(1/12)bh^3}{bh}} = \frac{1}{\sqrt{6}} h$$

### Product of Inertia

$$I_{xy} = \int_A xy \, dA = \int_A xy (\frac{1}{2} dx dy)$$

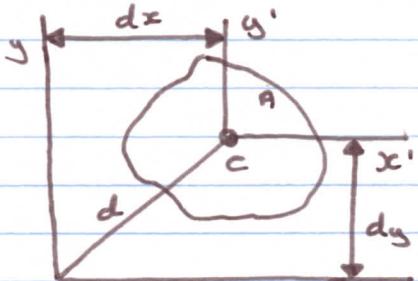
$$= \frac{1}{2} \int_a^b \int_0^h xy \, dx dy = \frac{1}{2} \left[ \frac{x^2}{2} \right]_0^b \left[ \frac{y^2}{2} \right]_0^h = \frac{b^2 h^2}{8}$$

### Polar moment of Inertia

$$J_o = I_x + I_y = \frac{1}{12} b h^3 + \frac{1}{4} h b^3$$

$$\text{and } M_o = \sqrt{M_{x_0}^2 + M_{y_0}^2} = \sqrt{\frac{1}{6} h^2 + \frac{1}{2} b^2}$$

### 2 - Parallel Axis Theorems



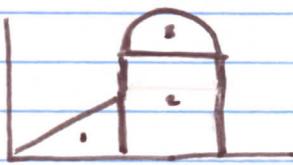
$$I_x = I_{x'} + d y^2 A$$

$$I_y = I_{y'} + d x^2 A$$

$$I_{xy} = I_{x'y'} + d x d y A$$

Centroid of an area  $A$ , and let  $x-y$  be a parallel coordinate system. The moments of inertia of  $A$  in terms of the two systems are related by the parallel axis theorem

$$J_o = J_{o'} + (dx^2 + dy^2) A = J_{o'} + d^2 A$$



where  $dx$  and  $dy$  are the coordinates of the centroid of  $A$  in the  $xy$ -coordinate system, and where  $d$  is the distance from the origin of the  $x'y'$ -coordinate system to the origin of the  $xy$ -coordinate system.

### 3 - Moments of Inertia of Composite Areas

Determining a moment of inertia of a composite area in terms of a given coordinate system involves three steps:

1 - Choose the parts - Try to divide the composite area into parts whose moments of inertia you know or can easily determine.

2 - Determine the moment of inertia of the parts. Determine the moment of inertia of each part in terms of a parallel coordinate system with its origin at the centroid of the part, then use the parallel axis theorem to determine the moment of inertia in terms of the given coordinate system.

3 - Sum the moments

Sum the moments of inertia of the parts (or subtract in the case of cutout) to obtain the moment of inertia of the composite area.

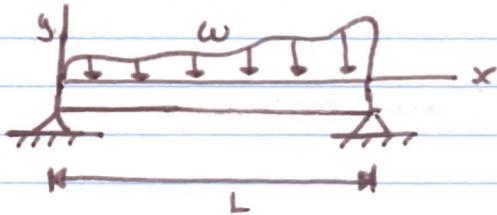
## Beams

- Loads distributed along a line

Let's assume that the function  $w$  describing a particular distributed load is known.

The graph of  $w$  is called the loading curve. The force acting on an element  $dx$  of the line is  $wdx$ . The total force  $F$  is:

$$F = \int_a^b w dx$$



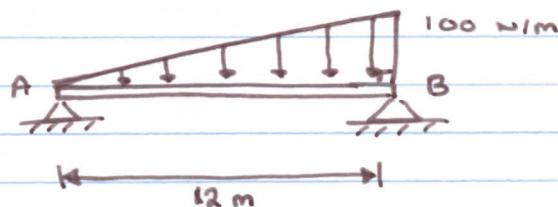
The moment about the origin due to the force exerted on the element  $dx$  is  $xw dx$ . So the total moment about the origin due to the distributed load is:

$$M = \int_a^b x w dx \quad \text{or} \quad M = \bar{x} F = \int_a^b x w dx$$

where  $F$  is the equivalent load placed at the position

$$\bar{x} = \frac{\int_a^b x w dx}{\int_a^b w dx}$$

Q - The beam is subjected to a triangular distributed load whose value at B is 100 N/m. Determine the reactions at A and B.



First Method :

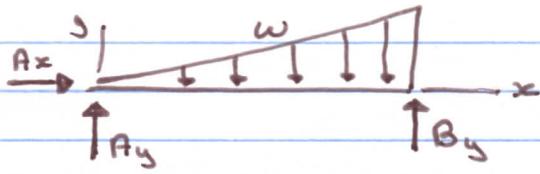
$$w = \frac{100x}{12} \text{ N/m}$$

The total load is:

$$F = \int_a^b w dx = \int_0^{12} \frac{100}{12} x dx \Rightarrow 600 \text{ N}$$

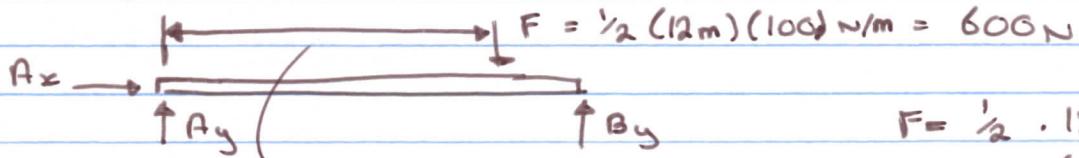
The clockwise moment about A due to the load is:

$$M_A = \int_L x \omega dx = \int_0^{12} \frac{100}{12} x dx = 4800 \text{ N/m}$$



$$\begin{aligned}\sum F_x &= A_x = 0 \\ \sum F_y &= A_y + B_y - 600 = 0 \\ \sum M_A &= 12(B_y) - 4800 = 0 \\ A_x &= 0 \\ A_y &= 200 \text{ N} \\ B_y &= 400 \text{ N}\end{aligned}$$

Second Method :



$$\begin{aligned}F &= \frac{1}{2} \cdot 12 \text{ m} \cdot 100 \text{ N/m} \\ &= 600 \text{ N} \\ \bar{x} &= \frac{2}{3} \cdot 12 \text{ m} = 8 \text{ m}\end{aligned}$$

$$\begin{aligned}\sum F_x &= 0 = A_x \\ \sum F_y &= A_y + B_y - 600 = 0 \\ \sum M_A &= 12B_y - 8 \cdot 600 = 0\end{aligned}$$

$$\begin{aligned}\therefore A_x &= 0 \\ A_y &= 200 \text{ N} \\ B_y &= 400 \text{ N}\end{aligned}$$