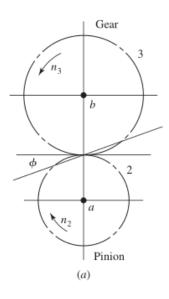
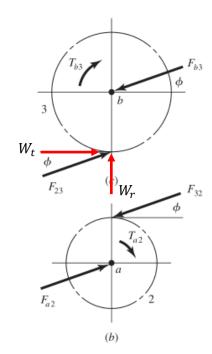
#### **Spur Gears**

# 13-14 Force Analysis - Spur Gearing

# Figure 13-32

Free-body diagrams of the forces and moments acting upon two gears of a simple gear train.





 $F_{23}$  and  $F_{32}$  are action and reaction forces;

Transmitted load:  $W_t = F_{23}cos\phi = F_{32}cos\phi$ ;

Radial load (separating force):  $W_r = F_{23} sin \phi = F_{32} sin \phi$ 

# **Determination of Transmitted Load**

**US-customary units** 

Pitch line velocity

$$V = \pi dn / 12 \tag{13-34}$$

Where d and n are pinion pitch diameter (in in) and pinion speed (in rpm), or gear pitch diameter (in in) and gear speed (in rpm). V is pitch line velocity in ft/min.

Transmitted Load  $W_t$  (or  $W^t$ ):

$$W_t = 33\ 000 \frac{H}{V} \tag{13-35}$$

Where H is power in hp; V is pitch-line speed in ft/min; and  $W_t$  is in lb.

SI Units

$$W_t = \frac{60\ 000H}{\pi dn} \tag{13-36}$$

Where H is power in kW; d is pitch diameter in mm (of pinion or gear); n is speed (of pinion or gear) in rpm; and  $W_t$  is in kN.

#### **Gear Materials**

#### Information from the 6th Ed.

Through-hardening: (by annealing, normalizing and annealing, and quench and temper)
 1040, 1060, 1335, 3135, 4037, 4140, 4340, 5150, 8640, and 8740, with 4140 and 4340 being the most commonly used.

#### Case hardening

By carburization (up to 600 HB): 4118, 4320, 4620, 4720, 4820, 5120, and 8620 By nitrization: 4140, 4340

#### Information from AGMA

- AGMA recommends to specify the following for gear materials:
  - Material designator or stress grade
  - Material cleanliness
  - o Surface and core hardness
  - AGMA quality level
- Gear materials are given a stress grade  $0 \sim 3$ .
  - 0: Ordinary quality. No gross defects but no close control of quality;
  - 1: Good quality. Modest control of most important quality items; used in typical industrial applications;
  - 2: Premium quality. Close control of all critical quality items; improved quality/performance but increased material cost;
  - 3: Superior quality. Absolute control of all critical quality items; ultimate performance but high material cost.

#### • Material *cleanliness*

This is by AMS, Aerospace Material Specification.

Grade 3 materials: call for AMS 2300 (Premium Aircraft-Quality Steel Cleanliness, Magnetic Particle Inspection).

Grade 2 materials: call for AMS 2301 (Cleanliness, Aircraft Quality Steel Magnetic Particle Inspection Procedure).

Grade 1 materials: not required to adhere to any AMS specification.

AGMA quality (or accuracy) level:

$Q_V$	Descriptive	Manufacture	Applications
14-15	Highest level	Trade secret	Highest load & reliability; high speed
12-13	High level	Grinding, shaving	Aerospace turbo-machinery
10-11	Relatively high	Grinding, shaving	Mass production; automotive vehicles; automotive
8-9	Good	Hobbing, shaping	Automotive; electric motor; industrial
6-7	Nominal	Hobbing, shaping (by older machines)	Low speed gears
4-5	Minimal	Casting, molding	Slow speed gears; toys, gadgets

# Chapter 14

#### 14-1: The Lewis Bending Equation

# 14-2: Surface Durability

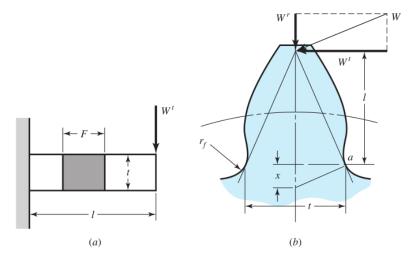
#### Main failure modes of gearing

- Bending fatigue → Breakage of the tooth
- Contact fatigue → Pitting and spalling
- Wear (due to adhesion, abrasion, corrosion, scoring, scuffing ...)

**Bending Fatigue** is caused by excessive dynamic bending stress at the base of the tooth;

**Surface Fatigue** is caused by repeated applications of loads on the surface.

Figure 14-1 and the Lewis Bending Equation



A tooth is considered a cantilever beam;

Transmitted and radial loads are labelled  $W^t$  and  $W^r$ ;

Span of beams depends on tooth geometry;

Bending stress at "fixed end": by (Eq. 14-2) or (Eq. 14-3);

$$\sigma = \frac{W^t P}{FY} \tag{14-2}$$

$$Y = \frac{2xP}{3} \tag{14-3}$$

Dynamic effects: (Eq. 14-7) or (Eq. 14-8);

$$\sigma = \frac{K_v W^t P}{FY} \tag{14-7}$$

$$\sigma = \frac{K_v W^t}{FmY} \tag{14-8}$$

Example 14-1: Applying above equations to determine required horsepower;

Example 14-2: Fatigue due to bending stress for infinite life;

Drawbacks: compressive stress due to  $W^r$  is not considered.

### **Surface Durability**

At the contact point, each tooth is considered part of a cylindrical surface;

Hertz contact theory: see Sec. 3-19;

Contract stress: (Eq. 14-14);

$$\sigma_C = -C_p \left[ \frac{K_v W^t}{F \cos \phi} \left( \frac{1}{r_1} + \frac{1}{r_2} \right) \right]^{1/2}$$
 (14-14)

**Example 14-3:** Applying the above equation;

Drawbacks: fatigue due to contact stress is not considered.

#### 14-3: AGMA Stress Equations

### **Stress Numbers**

- In AGMA terminology, a stress caused by an applied load is a stress number.
- There are two stress numbers: bending and contact.

Bending Stress Number (for spur and helical gears)

$$\sigma = \begin{cases} W^{t}K_{o}K_{v}K_{s}\frac{P_{d}}{F}\frac{K_{m}K_{B}}{J} & \text{(U.S. customary units)} \\ W^{t}K_{o}K_{v}K_{s}\frac{1}{bm_{t}}\frac{K_{H}K_{B}}{Y_{I}} & \text{(SI units)} \end{cases}$$

Contact Stress Number (for spur and helical gears)

$$\sigma_{c} = \begin{cases} C_{p} \sqrt{W^{t} K_{o} K_{v} K_{s} \frac{K_{m}}{d_{p} F} \frac{C_{f}}{I}} & \text{(U.S. customary units)} \\ Z_{E} \sqrt{W^{t} K_{o} K_{v} K_{s} \frac{K_{H}}{d_{v} \cdot b} \frac{Z_{R}}{Z_{I}}} & \text{(SI units)} \end{cases}$$

#### 14-4 AGMA Strength Equations

#### **Allowable Stress Numbers**

- In AGMA terminology, an allowable stress is an allowable stress number.
- There are two allowable stress numbers: allowable bending and allowable contact.

Allowable Bending Stress Number (for spur and helical gears)

$$\sigma_{\text{all}} = \begin{cases} \frac{S_t}{S_F} \frac{Y_N}{K_T K_R} & \text{(U.S. customary units)} \\ \frac{S_t}{S_F} \frac{Y_N}{Y_\theta Y_Z} & \text{(SI units)} \end{cases}$$

(Where  $S_F$  is factor of safety)

Allowable Contact Stress (for spur and helical gears)

$$\sigma_{c,\text{all}} = \begin{cases} \frac{S_c}{S_H} \frac{Z_N C_H}{K_T K_R} & \text{(U.S. customary units)} \\ \frac{S_c}{S_H} \frac{Z_N Z_W}{Y_\theta Y_Z} & \text{(SI units)} \end{cases}$$

(Where  $S_H$  is factor of safety)

## 14-18 Analysis

#### Figures 14-17 and 14-18

Summary of above formulas (US-customary units only), including where to find the factors.

Overload Factors K<sub>o</sub>

Table of Overload Factors,  $K_0$ 

Driven Machine					
Power source	Uniform	Moderate shock	Heavy shock		
Uniform	1.00	1.25	1.75		
Light shock	1.25	1.50	2.00		
Medium shock	1.50	1.75	2.25		

Examples of power sources and driven machines in each "shock" category (courtesy Mechanical Design of Machine Elements and Machines, A Failure Prevention Perspective, J.A. Collins, Wiley & Sons, 2003).

#### Power sources:

- Uniform: electric motors, steam turbines, gas turbines;
- Light shock: multi-cylinder engines;
- Medium Shock: single-cylinder engines.

#### Driven machines:

- Uniform: generators; uniformly loaded conveyors;
- Medium Shock: centrifugal pumps, reciprocating pumps and compressors, heavy-duty conveyors, main drives of machine tools;
- Heavy Shock: punch press, crushers, shears, power shovels.

**Example 14-4:** Spur gears **Example 14-5:** Helical gears

# 14-19 Design of a Gear Mesh

#### **Initial Steps**

- Choose a diametral pitch; (P = 8, or 10 teeth/in)
- Select face width and material;
- Decide on core and surface hardness for pinion and gear, and other details such as reliability, etc.

With the second and third steps above, iteration back to the first step may be necessary.

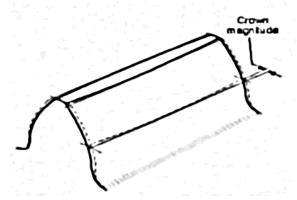
#### **Detailed Calculations**

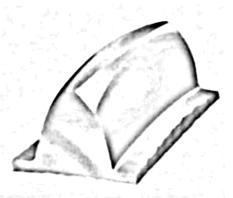
- Referring to page 768;
- It shows all factors, and four factors of safety. They are, one for pinion bending, one for gear bending, one for pinion contact, and one for gear contact.

#### **Example:**

A gearbox contains a set of spur ears. IT is driven by a single cylinder engine, and to drive a reciprocating compressor. Output shaft rotates at 1500 rpm, with a maximum torque of 550 lb-in. Gear ratio is 2.5:5 to 1. Pitch diameter of pinion Is expected to be around 3.25". Assume:

- (1) AGMA grade 1 steel through hardened to  $H_B = 350$  for pinion and 280 for gear;
- (2) 20° full depth and uncrowned teeth;
- (3)  $Q_V = 10$ ;
- (4) 10-year life of 8-hour shift continuous operation;
- (5) Gears are located in the mid-span of their respective shafts;
- (6) 99% reliability.
- (7) Oil temperature is less than  $250^{\circ}F$





#### <u>Solution</u>

1. Choose  $P = 10 \frac{teeth}{in}$ 

$$N_P = P \cdot d_p = (10)(3.25) = 32.5 - \text{Select } N_p = 33$$

$$N_G = (2.5)(33) = 82.5$$
 - Select  $N_G = 83$ .

So  $N_P=33$ ,  $d_p=3.3$ ,  $N_G=83$ ,  $d_{\rm G}=8.3$ ,  $20^{\circ}$  full depth and uncrowned teeth.

Contact ratio is:

$$m_c = \frac{0.81145 + 1.6896 - 1.9837}{\left(\frac{\pi}{10}\right)\cos(20^\circ)} = 1.7525$$

2. Face width  $F = (3\sim 5)p = 4p = 1.26$ "; Choose F = 1.25".

3. Transmitted load

$$W^{t} = \frac{T_{max}}{r_{G}} = \frac{500}{\left(\frac{8.3}{2}\right)} = 132.5 \ lb$$

4. AGMA allowable stress numbers

Tables 14-3 and 14-6 indicate what to use, based on gear materials.

Pinion:  $H_B = 350$ ,  $S_t = 39,855 \ psi$ ,  $S_c = 141,800 \ psi$ Gear:  $H_B = 280$ ,  $S_t = 34,444 \ psi$ ,  $S_c = 119,260 \ psi$ 

5. Geometry factors

For bending:  $J_P = 0.4$ ,  $J_G = 0.445$ 

For contact: use (Eq. 14-23) where  $m_N$  is the load sharing ratio, and  $m_G$  is the speed ratio.

$$I = \begin{cases} \frac{\cos \phi_t \sin \phi_t}{2m_N} \frac{m_G}{m_G + 1} & \text{external gears} \\ \frac{\cos \phi_t \sin \phi_t}{2m_N} \frac{m_G}{m_G - 1} & \text{internal gears} \end{cases}$$
(14-23)

That is,  $m_N=1$  (for spur gears), and  $m_G=\frac{83}{33}=2.515$ .

So, 
$$I = 0.115$$

6. Elastic coefficient

$$C_P = 2300\sqrt{psi}$$

Table 14-8

Elastic Coefficient  $C_p$  ( $Z_E$ ),  $\sqrt{\text{psi}}$  ( $\sqrt{\text{MPa}}$ ) Source: AGMA 218.01

Pinion Material	Gear Material and Modulus of Elasticity E <sub>C</sub> , lbf/in² (MPa)*						
	Pinion Modulus of Elasticity E <sub>p</sub> psi (MPa)*	Steel 30 × 10 <sup>6</sup> (2 × 10 <sup>5</sup> )	Malleable Iron $25 \times 10^6$ $(1.7 \times 10^5)$	Nodular Iron 24 × 10 <sup>6</sup> (1.7 × 10 <sup>5</sup> )	Cast Iron 22 × 10 <sup>6</sup> (1.5 × 10 <sup>5</sup> )	Aluminum Bronze $17.5 \times 10^6$ $(1.2 \times 10^5)$	Tin Bronze 16 × 10 <sup>6</sup> (1.1 × 10 <sup>5</sup> )
Steel	$30 \times 10^{6}$	2300	2180	2160	2100	1950	1900
	(2 × 10 <sup>5</sup> )	(191)	(181)	(179)	(174)	(162)	(158)
Malleable iron	$25 \times 10^{6}$	2180	2090	2070	2020	1900	1850
	(1.7 × 10 <sup>5</sup> )	(181)	(174)	(172)	(168)	(158)	(154)
Nodular iron	$24 \times 10^{6}$	2160	2070	2050	2000	1880	1830
	(1.7 × 10 <sup>5</sup> )	(179)	(172)	(170)	(166)	(156)	(152)
Cast iron	$22 \times 10^6$	2100	2020	2000	1960	1850	1800
	(1.5 × 10 <sup>5</sup> )	(174)	(168)	(166)	(163)	(154)	(149)
Aluminum bronze	$17.5 \times 10^{6}$	1950	1900	1880	1850	1750	1700
	$(1.2 \times 10^{5})$	(162)	(158)	(156)	(154)	(145)	(141)
Tin bronze	$16 \times 10^6$	1900	1850	1830	1800	1700	1650
	(1.1 × 10 <sup>5</sup> )	(158)	(154)	(152)	(149)	(141)	(137)

Poisson's ratio = 0.30.

#### 7. Dynamic factor

 $Q_V = 10$ ; So B = 0.39685, A = 83.776

Pitch line velocity  $V = \pi d_G n_G/12 = 3259 \ ft/min$ 

(Eq. 14-29): max. pitch line velocity  $V_{max} = 8240 \ ft/min$ 

$$(V_t)_{\text{max}} = \begin{cases} [A + (Q_v - 3)]^2 & \text{ft/min} \\ \frac{[A + (Q_v - 3)]^2}{200} & \text{m/s} \end{cases}$$
 (14-29)

(Eq. 14-27):  $K_V = 1.229$ 

$$K_v = \begin{cases} \left(\frac{A + \sqrt{V}}{A}\right)^B & V \text{ in ft/min} \\ \left(\frac{A + \sqrt{200V}}{A}\right)^B & V \text{ in m/s} \end{cases}$$
(14-27)

#### 8. Overload factor

$$K_o = 1.75$$

# 9. Surface-condition factor

 $C_r = 1$  (currently as a place holder)

#### 10. Size factor

$$K_s = \frac{1}{k_b} = 1.192 \left(\frac{F\sqrt{Y}}{P}\right)^{0.0535}$$

F=1.25",  $P=10\ teeth/in$ , Y is the Lewis form factor from Table 14-2. By linear interpolation,  $Y_P=0.368$ ,  $Y_G=0.439$ .

So, 
$$K_{SP} = 1.038$$
,  $K_{SG} = 1.043$ 

Note: if calculated value is less than 1, set  $K_s = 1$ .

<sup>\*</sup>When more exact values for modulus of elasticity are obtained from roller contact tests, they may be used

#### 11. Load distribution factor

Sec. 14-11 lists conditions under which to use (Eq. 14-30 through (Eq. 14-35).

$$C_{mc} = \begin{cases} 1 & \text{for uncrowned teeth} \\ 0.8 & \text{for crowned teeth} \end{cases}$$
 (14–31)

then  $C_{mc} = 1$ 

$$C_{pf} = \begin{cases} \frac{F}{10d_P} - 0.025 & F \le 1 \text{ in} \\ \frac{F}{10d_P} - 0.0375 + 0.0125F & 1 < F \le 17 \text{ in} \\ \frac{F}{10d_P} - 0.1109 + 0.0207F - 0.000 228F^2 & 17 < F \le 40 \text{ in} \end{cases}$$
 then  $C_{pf} = 0.01600$ 

then  $C_{pf} = 0.01600$ 

$$C_{pm} = \begin{cases} 1 & \text{for straddle-mounted pinion with } S_1/S < 0.175 \\ 1.1 & \text{for straddle-mounted pinion with } S_1/S \ge 0.175 \end{cases}$$
 (14–33)

then  $C_{pm} = 1$ 

$$C_{ma} = A + BF + CF^2$$
 (see Table 14–9 for values of A, B, and C) (14–34)

then  $C_{ma} = 0.1466$  (commercial, enclosured units)

$$C_e = \begin{cases} 0.8 & \text{for gearing adjusted at assembly, or compatibility} \\ & \text{is improved by lapping, or both} \\ 1 & \text{for all other conditions} \end{cases}$$
 (14–35)

then  $C_e = 1$ 

(Eq. 14-30):  $K_m = 1.163$ 

$$K_m = C_{mf} = 1 + C_{mc}(C_{pf}C_{pm} + C_{ma}C_e)$$
 (14–30)

12. Hardness-ratio factor

$$\begin{split} \frac{H_{BP}}{H_{BG}} &= \frac{350}{280} = 1.25 \\ A' &= 0.002935 \\ \text{(Eq. 14-36): } C_{Hg} &= 1.004; \text{ but } C_{HP} = 1. \end{split}$$

### 13. Stress-cycle factors

For pinion, 
$$n_p = \left(\frac{83}{33}\right) \cdot n_G = 3772.7 \ rpm$$

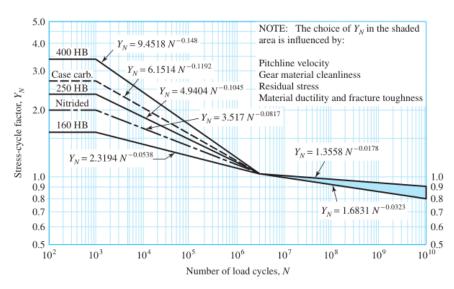
Pinion's life 
$$N = (10)(365)(8)(60)(3772.7) = 6.610(10^9)$$
 revs

Figure 14-14: 
$$Y_{NP} = 1.6831 \cdot N^{-0.0323} = 0.8108$$

Figure 14-15: 
$$Z_{NP} = 2.466 \cdot N^{-0.056} = 0.6951$$

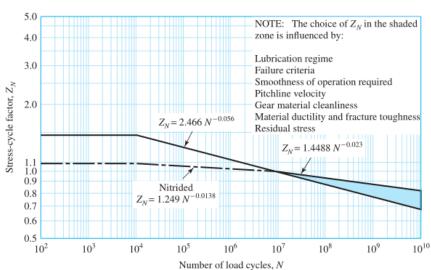
# **Figure 14-14**

Repeatedly applied bending strength stress-cycle factor  $Y_N$ . (ANSI/AGMA 2001-D04.)



# Figure 14-15

Pitting resistance stress-cycle factor  $Z_N$ . (ANSI/AGMA 2001-D04.)



Gears life  $N = (10)(365)(8)(60)(1500) = 2.628(10^9)$  revs

Figure 14-14:  $Y_{NG} = 1.6831 \cdot N^{-0.0323} = 0.8353$ 

Figure 14-15:  $Z_{NG} = 2.466 \cdot N^{-0.056} = 0.7320$ 

# 14. Reliability factor

Table 14-10 or (Eq. 14-38):

$$K_R = 1$$

$$K_R = \begin{cases} 0.658 - 0.0759 \ln(1 - R) & 0.5 < R < 0.99 \\ 0.50 - 0.109 \ln(1 - R) & 0.99 \le R \le 0.9999 \end{cases}$$
 (14-38)

# 15. Temperature factor

Just use  $K_T = 1$  (Valid for processes up to  $250^{\circ}F$ )

#### 16. Rim-thickness factor

(Eq. 14-40):  $K_B=1$  (but need to ensure  $m_B\geq 1.2$ )

$$K_B = \begin{cases} 1.6 \ln \frac{2.242}{m_B} & m_B < 1.2\\ 1 & m_B \ge 1.2 \end{cases}$$
 (14-40)

# 17. Safety factor $S_F$ and $S_H$

They are to be determined from AGMA equations.

$$\sigma_P = 6,880 \ psi$$

$$\sigma_G = 6,214 \text{ psi}$$

$$\sigma_{all,P} = \frac{32,314}{S_{F,P}}$$
 
$$\sigma_{all,G} = \frac{28,771}{S_{F,G}}$$

$$S_{F,P} = 4.70$$

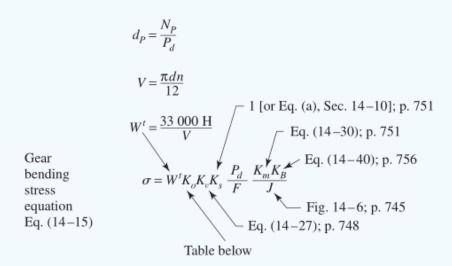
$$S_{F,G} = 4.63$$

Similarly,

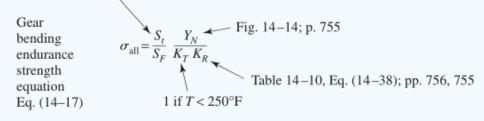
$$S_{H,P} = 1.49$$

$$S_{H,G} = 1.41$$

# SPUR GEAR BENDING Based on ANSI/AGMA 2001-D04 (U.S. customary units)



 $_{0.99}(S_t)_{10}$ 7 Tables 14–3, 14–4; pp. 740, 741



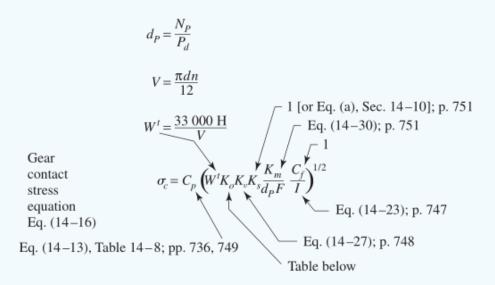
Bending factor of safety 
$$S_F = \frac{S_t Y_N / (K_T K_R)}{\sigma}$$
 Eq. (14–41)

Remember to compare  $S_F$  with  $S_H^2$  when deciding whether bending or wear is the threat to function. For crowned gears compare  $S_F$  with  $S_H^3$ .

Table of Overload Factors,  $K_o$ 

Driven Machine				
Power source	Uniform	Moderate shock	Heavy shock	
Uniform	1.00	1.25	1.75	
Light shock	1.25	1.50	2.00	
Medium shock	1.50	1.75	2.25	

# SPUR GEAR WEAR Based on ANSI/AGMA 2001-D04 (U.S. customary units)



Gear contact endurance strength Eq. (14–18)

Gear 
$$\sigma_{c,\text{all}} = \frac{S_c Z_N C_H}{S_H K_T K_R}$$

Section 14–12, gear only; pp. 753, 754

Table 14–10, Eq. (14–38); pp. 756, 755

Gear only

Gear only

Gear only

factor of safety Eq. (14–42)

Remember to compare  $S_F$  with  $S_H^2$  when deciding whether bending or wear is the threat to function. For crowned gears compare  $S_F$  with  $S_H^3$ .

# Table of Overload Factors, $K_o$

Driven Machine				
Power source	Uniform	Moderate shock	Heavy shock	
Uniform	1.00	1.25	1.75	
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Medium shock	1.50	1.75	2.25	