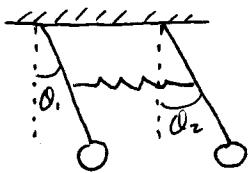
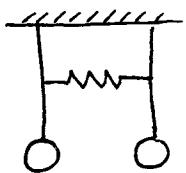
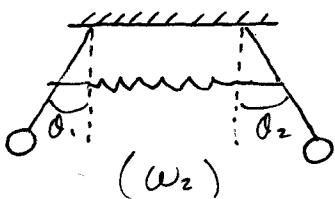


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$$\text{; where } \frac{\Omega_1}{\Omega_2} = 1$$

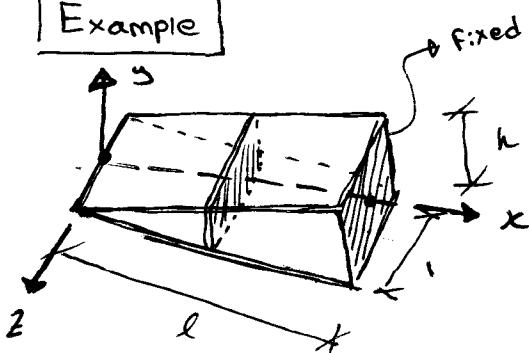
 (ω_1)  (ω_2)

beam bending

$$\omega^2 = \frac{\int_0^l EI(y'')^2 dx}{\int_0^l P A y^2 dx}$$

Here, $y = y(x)$: the assumed deflection $y(x)$: the static deflection ω^2 : an approximation of the fundamental freq. of the beam

Example



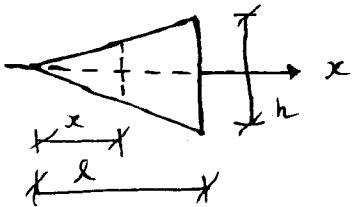
E is constant, estimate first natural frequency.

Solution: $y(x)$ trial function

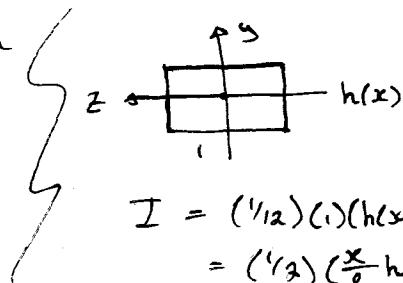
$$\text{then } y(l) = 0, y'(l) = 0$$

$$\text{Let } y(x) = \left[1 - \left(\frac{x}{l}\right)\right]^2$$

→ side view



$$h(x) = \left(\frac{x}{l}\right)h$$



$$\begin{aligned} I &= \left(\frac{l}{12}\right)(1)(h(x)^3) \\ &= \left(\frac{l}{3}\right)\left(\frac{x}{l}h\right)^3 \end{aligned}$$

Since $\frac{y''}{l^2} = \frac{2}{l^2}$

$$\therefore \omega^2 = \frac{\int_0^l E \cdot (1/12) \left(\frac{x}{l} h\right)^3 \cdot \left(\frac{2}{l^2}\right)^2 dx}{\int_0^l \rho \frac{x}{l} h \left[\left(1 - \frac{x}{l}\right)^2\right]^2 dx} = 2.6 \frac{Eh^2}{\rho l^4}$$

$$\omega = 1.5811 \sqrt{\frac{Eh^2}{\rho l^4}} \quad \left\{ \begin{array}{l} \omega_{\text{exact}} = 1.5343 \sqrt{\frac{Eh^2}{\rho l^4}} \end{array} \right.$$

- Matrix iteration method

$$[M]\ddot{\vec{x}} + [K]\vec{x} = \emptyset$$

The natural Frequency and mode shape:

$$(-\omega^2 [M] + [K])\vec{x} = \emptyset$$

$$[K]^{-1}(-\omega^2 [M] + [K])\vec{x} = \emptyset$$

$$\Rightarrow (-\omega^2 [K]^{-1}[M] + [I])\vec{x} = \emptyset$$

$$\text{Define: } [D] = [K]^{-1}[M] \quad ; \quad \lambda = 1/\omega^2$$

$$\Rightarrow ([D] - \lambda[I])\vec{x} = \emptyset$$

$$\text{then } [D]\vec{x} = \lambda\vec{x}$$

$$1^\circ: \vec{x} = \vec{x}_1 (\neq \emptyset)$$

$$2^\circ: [D]\vec{x}_1 = \vec{x}_2$$

$$[D]\vec{x}_2 = \vec{x}_3$$

⋮

$$[D]\vec{x}_r = \vec{x}_{r+1} \approx 2\vec{x}_r$$

$$\vec{x}_r = \begin{Bmatrix} x_{1,r} \\ x_{2,r} \\ \vdots \\ x_{n,r} \end{Bmatrix} \quad \vec{x}_{r+1} = \begin{Bmatrix} x_{1,r+1} \\ x_{2,r+1} \\ \vdots \\ x_{n,r+1} \end{Bmatrix}$$

$$\frac{x_{1,r+1}}{x_{1,r}} = \frac{x_{2,r+1}}{x_{2,r}} = \dots = \frac{x_{n,r+1}}{x_{n,r}} \approx \frac{x_{n,r+1}}{x_{n,r}} \approx \lambda$$

Given $[D] : \lambda_1, \lambda_2, \dots, \lambda_n$
 $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$

Then $\vec{x}_1 = c_1 \vec{u}_1 + c_2 \vec{u}_2 + \dots + c_n \vec{u}_n \quad (c_n \neq 0)$
 $\vec{x}_2 = [D] \vec{x}_1 = c_1 [D] \vec{u}_1 + c_2 [D] \vec{u}_2 + \dots + c_n [D] \vec{u}_n$
 $\vec{x}_2 = c_1 \lambda_1 \vec{u}_1 + c_2 \lambda_2 \vec{u}_2 + \dots + c_n \lambda_n \vec{u}_n$
 $\vec{x}_3 = [D] \vec{x}_2 = c_1 \lambda_1^2 \vec{u}_1 + c_2 \lambda_2^2 \vec{u}_2 + \dots + c_n \lambda_n^2 \vec{u}_n$
 \vdots (thus...)
 $\vec{x}_r = c_1 \lambda_1^{r-1} \vec{u}_1 + c_2 \lambda_2^{r-1} \vec{u}_2 + \dots + c_n \lambda_n^{r-1} \vec{u}_n$
 $\vec{x}_{r+1} = c_1 \lambda_1^r \vec{u}_1 + c_2 \lambda_2^r \vec{u}_2 + \dots + c_n \lambda_n^r \vec{u}_n$

When \vec{x} is large enough:

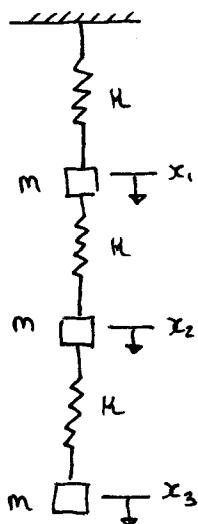
$$\vec{x}_r \approx c_n \lambda_n^{r-1} \vec{u}_n$$

$$\vec{x}_{r+1} \approx c_n \lambda_n^r \vec{u}_n$$

$$(\lambda_1 < \lambda_2 < \dots < \lambda_n)$$

Examples

Find the natural freq. using iteration method.



Solution: $[M] = \begin{bmatrix} m & 0 & 0 \\ 0 & m & 0 \\ 0 & 0 & m \end{bmatrix} = m \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$[K] = K \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

$$[D] = [K]^{-1}[M] = \frac{m}{K} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{bmatrix}$$

$$\text{Consider: } ([D_1] - 2[I])x = 0$$

Let: $\lambda = \frac{K}{m} \cdot \frac{1}{\omega^2} \Rightarrow [D_1] = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{bmatrix}$

(for this example only)

Take $\vec{x}_1 = \begin{Bmatrix} 1 \\ 1 \\ 1 \end{Bmatrix}$

Then $\vec{x}_2 = [D]\vec{x}_1 = \begin{Bmatrix} 3 \\ 5 \\ 6 \end{Bmatrix} = 3 \begin{Bmatrix} 1 \\ 1.666\bar{7} \\ 2 \end{Bmatrix}$

$$\vec{x}_3 = [D]\vec{x}_2 = [D] \begin{Bmatrix} 1 \\ 1.666\bar{7} \\ 2 \end{Bmatrix} = \begin{Bmatrix} 4.666\bar{7} \\ 8.333\bar{3} \\ 10.333\bar{3} \end{Bmatrix}$$

$$= (4.666\bar{7}) \begin{Bmatrix} 1 \\ 1.785\bar{7} \\ 2.214\bar{3} \end{Bmatrix}$$

$$\vec{x}_4 = [D]\vec{x}_3 = [D] \begin{Bmatrix} 1 \\ 1.785\bar{7} \\ 2.214\bar{3} \end{Bmatrix} = \begin{Bmatrix} 5.00000 \\ 9.00000 \\ 11.214\bar{3} \end{Bmatrix}$$

$$= (5.00000) \begin{Bmatrix} 1 \\ 1.80000 \\ 2.34286 \end{Bmatrix}$$

After 4 iterations :

$$= (5.04892) \begin{Bmatrix} 1.00000 \\ 1.80194 \\ 2.24698 \end{Bmatrix}$$

$$\therefore \lambda = 5.04892, \vec{u} = \begin{Bmatrix} 1 \\ 1.80194 \\ 2.24698 \end{Bmatrix}$$

$$\therefore w = \sqrt{\frac{1}{2}} \cdot \sqrt{\frac{k}{m}} = 0.44504 \sqrt{k/m}$$

The largest freq:

$$(-\omega^2 [M] + [K]) \vec{x} = 0$$

$$\Rightarrow (-\omega^2 [I] + [M]^{-1}[K]) \vec{x} = 0$$

$$\Rightarrow [M]^{-1}[K] \vec{x} = \omega^2 \vec{x}$$

Define: $[E] = [M]^{-1}[K]$

$$[E]\vec{x} = \omega^2 \vec{x} = \lambda \vec{x}$$

Iteration: $\vec{x}_2 = [E]\vec{x}_1$

$$\vec{x}_3 = [E]\vec{x}_2$$

⋮

$$\vec{x}_{r+1} = [E]\vec{x}_r$$

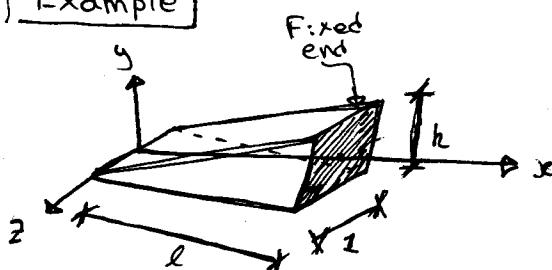
↓

$$\omega_n \text{ and } \vec{u}_n$$

Rayleigh-Ritz Method :

$$\omega^2 = \frac{\int_0^l EI(y'')^2 dx}{\int_0^l PA y^2 dx}$$

Example



Solution:

$$y_1 = (1 - x/l)^2$$

$$y_2 = (1 - x/l)^2 (x/l)$$

$$\text{Let } y(x) = c_1 y_1 + c_2 y_2$$

$$\text{Then } \omega^2 = \frac{\int_0^l EI(c_1 y_1'' + c_2 y_2'')^2 dx}{\int_0^l PA(c_1 y_1 + c_2 y_2)^2 dx}$$

$$\Rightarrow \omega^2(c_1, c_2) = \frac{P(c_1, c_2)}{Q(c_1, c_2)}$$

where $\omega^2(c_1, c_2)$: stationary value

$$\frac{\partial \omega^2}{\partial c_1} = 0 ; \quad \frac{\partial \omega^2}{\partial c_2} = 0$$

$$\frac{\partial \omega^2}{\partial c_1} = \frac{\partial}{\partial c_1} \left(\frac{P}{Q} \right) = \frac{\partial P}{\partial c_1} \cdot \frac{1}{Q} + P \cdot \left(\frac{-1}{Q^2} \right) \frac{\partial Q}{\partial c_1} = 0$$

$$\Rightarrow \frac{\partial P}{\partial c_1} - \frac{P}{Q} \frac{\partial Q}{\partial c_1} = 0$$

$$\frac{\partial P}{\partial c_1} - \omega^2 \frac{\partial Q}{\partial c_1} = 0$$

$$P = \int_0^l EI(c_1 y_1'' + c_2 y_2'')^2 dx$$

$$= \int_0^l EI(c_1^2 y_1''^2 + 2c_1 c_2 y_1'' y_2'' + c_2^2 y_2''^2) dx$$

$$= c_1^2 \int_0^l EI y_1''^2 dx + 2c_1 c_2 \int_0^l EI y_1'' y_2'' dx + c_2^2 \int_0^l EI y_2''^2 dx$$

$$\Rightarrow \frac{\partial P}{\partial c_1} = 2c_1 \int_0^l EI y_1''^2 dx + 2c_2 \int_0^l EI y_1'' y_2'' dx + 0$$

$$Q = \int_0^l PA(c_1 y_1 + c_2 y_2)^2 dx$$

$$= c_1^2 \int_0^l PA y_1^2 dx + 2c_1 c_2 \int_0^l PA y_1 y_2 dx + c_2^2 \int_0^l PA y_2^2 dx$$

$$\Rightarrow \frac{\partial Q}{\partial c_1} = 2c_1 \int_0^l PA y_1^2 dx + 2c_2 \int_0^l PA y_1 y_2 dx + 0$$

$$\delta C_1 \int_0^l EI y_1''^2 dx + \delta C_2 \int_0^l EI y_2''^2 dx - \omega^2 (\delta C_1 \int_0^l \rho A y_1'^2 dx + \delta C_2 \int_0^l \rho A y_2'^2 dx) = 0$$

where $\frac{\partial \omega^2}{\partial C_2} = 0 \rightarrow \frac{\partial P}{\partial C_2} - \omega^2 \frac{\partial Q}{\partial C_2} = 0$

$$C_1 \int_0^l EI y_1''^2 dx + C_2 \int_0^l EI y_2''^2 dx \dots \\ \dots - \omega^2 (C_1 \int_0^l \rho A y_1'^2 dx + C_2 \int_0^l \rho A y_2'^2 dx) = 0$$

Matrix Form:

$$([K] - \omega^2 [M]) \begin{Bmatrix} C_1 \\ C_2 \end{Bmatrix} = 0$$

Here :

$$[K] = \begin{bmatrix} \int_0^l EI y_1''^2 dx & \xrightarrow{\text{same}} \int_0^l EI y_1'' y_2'' dx \\ \int_0^l EI y_1'' y_2'' dx & \int_0^l EI y_2''^2 dx \end{bmatrix}$$

$$[M] = \begin{bmatrix} \int_0^l \rho A y_1'^2 dx & \xrightarrow{\text{same}} \int_0^l \rho A y_1' y_2' dx \\ \int_0^l \rho A y_1' y_2' dx & \int_0^l \rho A y_2'^2 dx \end{bmatrix}$$

Since $A = \left(\frac{h}{l}\right)x$; $I = \frac{1}{12} \left(\frac{hx}{l}\right)^3$

$$\Rightarrow [K] = \begin{bmatrix} 0.0833333 & 0.0333333 \\ 0.0333333 & 0.0333333 \end{bmatrix} \frac{Eh^3}{l}$$

$$[M] = \begin{bmatrix} 0.0333333 & 0.00952381 \\ 0.00952381 & 0.0357143 \end{bmatrix} \rho h$$

\Rightarrow Solution :

$$\omega_1^2 = 2.35741 \frac{Eh^2}{\rho l^4}$$

$$\omega_2^2 = 24.9426 \frac{Eh^2}{\rho l^4}$$

The First Natural Frequency:

$$\omega_1 = 1.5353 \sqrt{Eh^2/\rho l^4}$$

For one term, $C_2 = 0$

$$\omega_1^2 = 2.50000 \frac{Eh^2}{\rho l^4}$$

$$\omega_1 = 1.5811 \sqrt{Eh^2/\rho l^4}$$

The exact solution

$$\omega_{1,\text{exact}} = 1.5343 \sqrt{Eh^2/\rho l^4}$$

Take more terms

$$y_3 = (1 - \frac{x}{l})^2 (\frac{x}{l})^2$$

$$y_5 = (1 - \frac{x}{l})^2 (\frac{x}{l})^4$$

$$y(x) = C_1 y_1 + C_2 y_2 + C_3 y_3 + C_4 y_4 + C_5 y_5$$

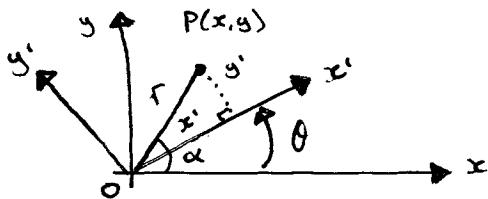
$$\Rightarrow \omega_1^2 = 2.364190 \text{ Eh/l}^4$$

$$\omega_1 = 1.53434 \sqrt{\text{Eh/l}^4}$$

* Correction: Units of $[K]$: $\frac{Eh^3}{l} \rightarrow \frac{Eh^3}{l^3}$
 (For last lecture) $[M] : \rho h \rightarrow \rho hl$

Jacobi's Method:

Coordinate transformation



$$x = r \cos \alpha$$

$$y = r \sin \alpha$$

$$P(x, y) \rightarrow P(x', y')$$

$$x' = r \cos(\alpha - \theta)$$

$$y' = r \sin(\alpha - \theta)$$

$$\rightarrow x' = r \cos \alpha \cos \theta + r \sin \alpha \cdot \sin \theta = x \cos \theta + y \sin \theta$$

$$y' = r \sin \alpha \cos \theta - r \cos \alpha \cdot \sin \theta = -x \sin \theta + y \cos \theta$$

$$\rightarrow \begin{Bmatrix} x' \\ y' \end{Bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{Bmatrix} x \\ y \end{Bmatrix}$$

$$\begin{Bmatrix} x \\ y \end{Bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{Bmatrix} x' \\ y' \end{Bmatrix}$$

$$\text{Define : } [Q] = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$[Q]^{-1} = [Q]^T$$

$$\text{Given } [D] = \begin{bmatrix} d_{11} & d_{12} \\ d_{21} & d_{22} \end{bmatrix} ; \text{ where } d_{12} = d_{21}$$

$$\rightarrow [Q]^T [D] [Q] = [D_1]$$

$$[D_1] = \begin{bmatrix} d_{11}^{\odot} & d_{12}^{\odot} \\ d_{21}^{\odot} & d_{22}^{\odot} \end{bmatrix}$$

$$\text{Here : } d_{12}^{\odot} = (\cos^2 \theta - \sin^2 \theta) d_{12} + (d_{22} - d_{11}) \sin \theta \cos \theta$$

$$d_{11}^{\odot} = d_{11} \cos^2 \theta + 2d_{12} \cos \theta \sin \theta + d_{22} \sin^2 \theta$$

$$d_{22}^{\odot} = d_{11} \sin^2 \theta - 2d_{12} \cos \theta \sin \theta + d_{22} \cos^2 \theta$$

$$\text{Let } d_{12}^0 = \emptyset$$

$$\Rightarrow \tan(2\theta) = \frac{2d_{12}}{d_{11} - d_{22}}$$

$$[D] = \begin{bmatrix} d_{11} & d_{12} & d_{13} \\ d_{21} & d_{22} & d_{23} \\ d_{31} & d_{32} & d_{33} \end{bmatrix}$$

$$[Q_1] = \begin{bmatrix} \cos\theta_1 & -\sin\theta_1 & \emptyset \\ \sin\theta_1 & \cos\theta_1 & \emptyset \\ \emptyset & \emptyset & 1 \end{bmatrix}$$

$$[Q_1]^T [D] [Q_1] = [D_1] = \begin{bmatrix} d_{11}^0 & \emptyset & d_{13}^0 \\ \emptyset & d_{22}^0 & d_{23}^0 \\ d_{31}^0 & d_{32}^0 & d_{33}^0 \end{bmatrix}$$

$$[Q_2] = \begin{bmatrix} \cos\theta_2 & \emptyset & -\sin\theta_2 \\ \emptyset & 1 & \emptyset \\ \sin\theta_2 & \emptyset & \cos\theta_2 \end{bmatrix}$$

$$[Q_2]^T [D_1] [Q_2] = [D_2] = \begin{bmatrix} d_{11}^0 & d_{12}^0 & \emptyset \\ d_{21}^0 & d_{22}^0 & d_{23}^0 \\ \emptyset & d_{32}^0 & d_{33}^0 \end{bmatrix}$$

→ Repeat many times ...

$$[Q_m]^T \cdots [Q_2]^T [Q_1]^T [D] [Q_1] [Q_2] \cdots [Q_m]$$

$$= \begin{bmatrix} d_{11}^m & \emptyset & \emptyset \\ \emptyset & d_{22}^m & \emptyset \\ \emptyset & \emptyset & d_{33}^m \end{bmatrix}$$

$$\text{Define: } [U] = [Q_1] [Q_2] \cdots [Q_m]$$

$$\rightarrow [D][U] = [U][\Lambda]$$

$$[\Lambda] = \text{diag}(d_{11}^{(m)}, d_{22}^{(m)}, d_{33}^{(m)})$$

Example Find the eigenvalues by using Jacobi's method

$$[D] = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{bmatrix}$$

$$\underline{\text{Solution}} : \rightarrow \tan(2\theta) = \frac{2d_{12}}{d_{11} - d_{22}} = \frac{2 \times 1}{1 - 2} = -2$$

$$\theta = -0.653574$$

$$[Q_1] = \begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.8506 & 0.5257 & 0 \\ -0.5257 & 0.8506 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[Q_1]^T [D] [Q_1] = \begin{bmatrix} 0.3820 & 0 & -0.2008 \\ 0 & 2.618 & 2.227 \\ -0.2008 & 2.227 & 3 \end{bmatrix} = D_1$$

$$\rightarrow \tan(2\theta) = \frac{2d_{23}}{d_{22} - d_{33}} = \frac{2 \times 2.227}{2.618 - 3}$$

$$\theta = -0.7426$$

$$[Q_2] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta \\ 0 & \sin\theta & \cos\theta \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.7367 & -0.6762 \\ 0 & -0.6762 & 0.7367 \end{bmatrix}$$

$$[Q_2]^T [D_1] [Q_2] = \begin{bmatrix} 0.3820 & 0.1358 & -0.1479 \\ 0.5738 & 0 & 5.044 \\ 5.044 & 0 & \end{bmatrix} = D_2$$

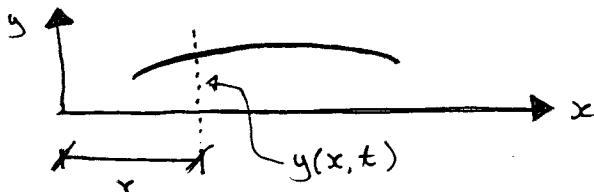
$$\rightarrow [Q_3]^T \cdots [Q_1]^T [D] [Q_1] \cdots [Q_3] = \begin{bmatrix} 0.3080 & 0.1762 \times 10^{-6} & 0 \\ 0.6431 & 7.02 \times 10^{-6} & 5.049 \\ \text{Sym.} & & \end{bmatrix}$$

$$\text{and } [U] = [Q_1][Q_2] \cdots [Q_3]$$

$$= \begin{bmatrix} 0.5910 & 0.7370 & 0.3280 \\ -0.7370 & 0.3280 & 0.5910 \\ 0.3280 & -0.5910 & 0.7370 \end{bmatrix}$$

(Column
Corresponds to)

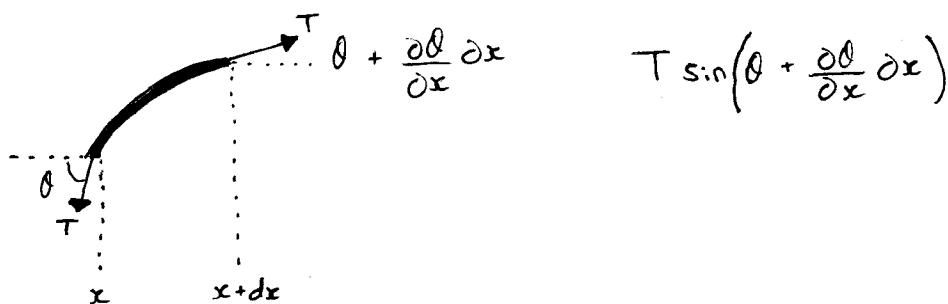
Vibrating String:



: the displacement is a function of both space and time.

Mass density per unit length: ρ

Small vibration, the tension: $T = \text{const.}$



$$T \sin(\theta + \frac{\partial \theta}{\partial x} dx) - T \sin \theta = \rho dx \frac{\partial^2 y}{\partial t^2}$$

$\theta \ll 1$, then $\sin \theta \approx 0$

$$T(\theta + \frac{\partial \theta}{\partial x} dx) - T\theta = \rho \frac{\partial^2 y}{\partial t^2} \frac{\partial \theta}{\partial x} dx$$

$$T(\frac{\partial \theta}{\partial x}) = \rho (\frac{\partial^2 y}{\partial t^2})$$

$$\theta \approx \tan \theta = \frac{\partial y}{\partial x}$$

$$\rightarrow T(\frac{\partial^2 y}{\partial x^2}) = \rho (\frac{\partial^2 y}{\partial t^2})$$

$$\boxed{(\frac{\partial^2 y}{\partial x^2}) = (\frac{1}{c^2})(\frac{\partial^2 y}{\partial t^2}) ; : c = \sqrt{T/\rho}}$$

→ wave speed

$$f(x-ct), g(x+ct)$$

$$\longrightarrow \qquad \longleftarrow$$

$$\rightarrow y(x, t) = f(x-ct) \cdot g(x+ct)$$

→ Harmonic Solution of time t

$$y(x, t) = Y(x) e^{i\omega t}$$

$$\frac{\partial^2 y}{\partial x^2} = Y''(x) e^{i\omega t}$$

$$\frac{\partial^2 y}{\partial t^2} = -\omega^2 Y(x) e^{i\omega t}$$

$$Y'' e^{i\omega t} = -\frac{\omega^2}{c^2} Y(x) e^{i\omega t} \rightarrow Y'' + \frac{\omega^2}{c^2} Y = 0 \quad (I)$$



At $x = 0$, $y(0, t) = Y(0) e^{i\omega t} = 0$
 $Y(0) = 0$ II

At $x = l$, $y(l, t) = Y(l) e^{i\omega t} = 0$
 $Y(l) = 0$ III

Boundary value problem.