

Feb. 11 / 19

$$\frac{F_{out}}{F_{in}} = \frac{V_{in}}{V_{out}}$$

$$F_{in}V_{in} = F_{out}V_{out}$$

For press example:

$$M_A = \frac{F_{out}}{F_{in}} ; \quad F_{out} = M_A \cdot F_{in} = \left(\frac{V_{in}}{V_{out}} \right) \cdot F_{in}$$

where ω_2 is given:

$$V_{in} = O_2 E \cdot \omega_2$$

Given $F_{in} = 100 \text{ lb}$, Find F_{out}

$$O_2 E = 21 \text{ mm}$$

$$V_{in} = \overline{O_2 E} \cdot \omega_2$$

$$V_c = V_{out}$$

IC. to find V_c

$$w_3, I_{13}$$

$$V_A = \overline{O_2 A} \omega_2 = I_{13} \overline{A} w_3$$

$$w_3 = \frac{\overline{O_2 A} \omega_2}{I_{13} \cdot \overline{A}}$$

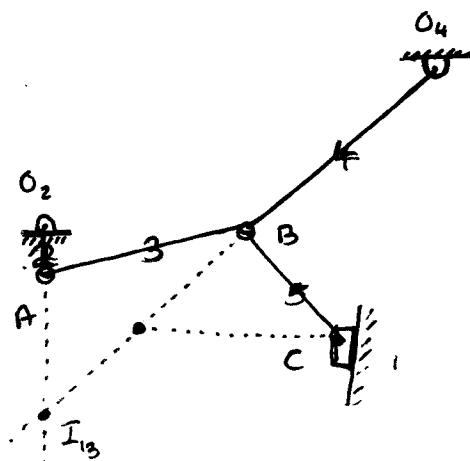
$$V_B = I_{13} \overline{B} \cdot w_3 = I_{13} \overline{B} \cdot w_5$$

$$w_5 = \frac{I_{13} \overline{B} \cdot O_2 A}{I_{13} \overline{B} \cdot I_{13} A} \omega_2$$

$$V_c = I_{13} C \cdot w_5 = V_{out}$$

$$F_{out} = \frac{O_2 E w_c}{I_{13} C w_5}$$

$$= 1.48 (100) = 148$$



a, b, c, d, θ_2, ω_2

Find ω_3, ω_4

1. Positional analysis to find θ_3, θ_4
2. $\hat{R}_2 + \hat{R}_3 - \hat{R}_4 - \hat{R}_1 = 0$
 $a e^{j\theta_2} + b e^{j\theta_3} - d - c e^{j\theta_4} = 0$

3. Differentiate it:

$$\underbrace{a_j \frac{d\theta_2}{dt} e^{j\theta_2}}_{\text{LHS}} + \underbrace{b_j \frac{d\theta_3}{dt} e^{j\theta_3}}_{\text{LHS}} - \underbrace{c_j \frac{d\theta_4}{dt} e^{j\theta_4}}_{\text{LHS}} = 0$$

$$\underbrace{a_j w_2 e^{j\theta_2}}_{\text{LHS}} + \underbrace{b_j w_3 e^{j\theta_3}}_{\text{LHS}} - \underbrace{c_j w_4 e^{j\theta_4}}_{\text{LHS}} = 0$$

$$\therefore \hat{V}_c = \hat{V}_a + \hat{V}_{B/A}$$

2 scalar eqns:

$$aw_2(\cos\theta_2 + j\sin\theta_2) + bw_3(\cos\theta_3 + j\sin\theta_3) - cw_4(\cos\theta_4 + j\sin\theta_4) = 0$$

$$jaw_2\cos\theta_2 - aw_2\sin\theta_2 + jbw_3\cos\theta_3 - bw_3\sin\theta_3 - jcw_4\cos\theta_4 + cw_4\sin\theta_4 = 0$$

Real parts:

$$-aw_2\sin\theta_2 - bw_3\sin\theta_3 + cw_4\sin\theta_4 = 0$$

Imaginary:

$$aw_2\cos\theta_2 + bw_3\cos\theta_3 - cw_4\cos\theta_4 = 0$$

$$\begin{bmatrix} -b\sin\theta_3 & \cos\theta_4 \\ b\cos\theta_3 & -c\cos\theta_4 \end{bmatrix} \begin{bmatrix} w_3 \\ w_4 \end{bmatrix} = \begin{bmatrix} aw_2\sin\theta_2 \\ -aw_2\cos\theta_2 \end{bmatrix}$$

$$j^2 = -1$$

$$\begin{bmatrix} w_3 \\ w_4 \end{bmatrix} = [A]^{-1}[B] \quad \text{where} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}}{(ad - cb)}$$

or determinant

$$\begin{aligned} w_3 &= \frac{ac(-\cos\theta_4\sin\theta_2 + \sin\theta_4\cos\theta_2)w_2}{bc(\sin\theta_3\cos\theta_4 - \cos\theta_3\sin\theta_4)} \\ &= \sin(\theta_3 - \theta_4) \end{aligned}$$

(3)

Example

(dimension in cm)

$$d = 6 ; a = 2 ; b = 7 ; c = 9 ; \rho = 6$$

$$\delta_3 = 30^\circ ; \theta_2 = 30^\circ ; \omega_2 = 10 \text{ rad/s}$$

 Find ω_3, ω_4, V_p
1. Position analysis

$$\theta_3 = 88.8^\circ, \theta_4 = 117.3^\circ$$

$$2. \omega_3 = \frac{2(10)}{7} \cdot \frac{\sin(117.3^\circ - 30^\circ)}{\sin(88.8^\circ - 117.3^\circ)} = -6 \text{ rad/s}$$

$$\omega_4 = \frac{2(10)}{9} \cdot \frac{\sin(30^\circ - 88.8^\circ)}{\sin(88.8^\circ - 117.3^\circ)} = -4 \text{ rad/s}$$

$$3. \hat{V}_p = \frac{j(2)(10)e^{j30^\circ}}{\hat{V}_A} + j(6)(-6)e^{j(88.8^\circ + 30^\circ)}$$

$$\hat{V}_A = 20(\cos(118.8^\circ) - j\sin(118.8^\circ)) \\ = 317.34 + 31.55$$

$$V_p = 21.55 + j34.66$$

$$|\hat{V}_p| = \sqrt{21.55^2 + 34.66^2} = 40.8 \text{ cm/s}$$

$$\theta = \tan^{-1}\left(\frac{34.66}{21.55}\right) = 58^\circ$$

Example

Point A

$$\hat{R}_2 - \hat{R}_1 - \hat{R}_4 - \hat{R}_3 = 0$$

$$ae^{j\theta_2} - de^{j\theta} - ce^{j\alpha\theta} - be^{j\beta\theta} = 0$$

$$aj\omega_2 e^{j\theta_2} - d - \theta - bi\omega_3 e^{j\theta_3} = 0$$

$$\hat{V}_A - \hat{V}_B - \hat{V}_{AB} = 0$$

$$\hat{V}_A = \hat{V}_B + \hat{V}_{B/A}$$

Example 6-8

$$a = 40 \quad \theta_2 = 60^\circ$$

$$b = 120 \quad \omega_2 = -30 \text{ rad/s}$$

$$c = -20$$

Find ω_3, d

$$1.) \text{ Find } \theta_3 = 152.9^\circ$$

$$2.) \omega_3 = \frac{40}{120} \cdot \frac{\cos 60^\circ}{\cos 152.9^\circ} (-30) = 5.616 \text{ rad}$$

$$d = -40(-30) \sin 60^\circ + 120(5.616) \sin(152.9^\circ) = 1346 \text{ mm/s}$$

$$\hat{V}_A = j a \omega_2 e^{j\theta_2} = a \omega_2 e^{j(\theta_2 + 90^\circ)}$$

$$j = e^{j90^\circ}$$

$$\hat{V}_A = 1039.23 - j600$$

$$\hat{V}_{AB} = j b \omega_3 e^{j\theta_3} = -306.86 - j600$$

$$\hat{V}_B = \hat{V}_A + \hat{V}_{B/A} \Rightarrow \hat{V}_B = \hat{V}_A - V_{AB} = 1346 \text{ mm/s}$$