

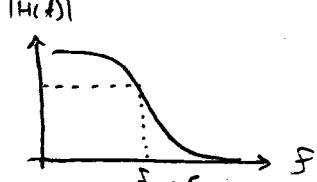
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Nov. 12/19

- Corresponding LPF (BW, CV-1 order) -  $H(s)$
- $\omega_c = 1 \text{ rad/s}$
- Get  $H(s)$
- Transform  $H(s) \rightarrow$  desired Filter  
Frequency transform

**Example 4.2**

Design a three-pole Butterworth low-pass filter with a bandwidth of 5 Hz.

Solution :

Given:

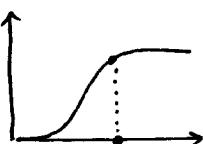
$$H(s) = \frac{(s-z_1)}{(s-p_1)(s-p_2)(s-p_3)}$$

$$H(s) = \frac{2s+1}{s^3 + 2s^2 + s + 4}$$

..... MATLAB

**Example 4.3**

Design a 3-pole high-pass filter with cutoff frequency  $\omega = 4 \text{ Hz}$

Solution :

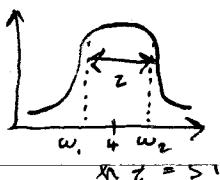
$$\omega_c = 4 \text{ Hz}$$

$$\omega_c = 2\pi \times 4 \text{ (rad/s)}$$

**Example 4.4**

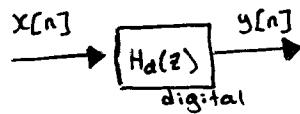
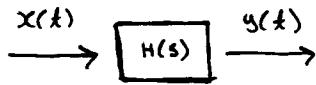
In example 4.2, a three-pole Butterworth lowpass filter was transformed to a bandpass filter with the passband centered at  $\omega = 4 \text{ Hz}$ .

The bandwidth is equal to 2 Hz.

Solution :

## 4.3 - Design of Digital Filters

### 1) Digital Filter



- DTFT (discrete time Fourier transform)

$$X(\Omega) = \sum_{n=0}^{N-1} x[n] e^{-j\Omega n} ; \text{ where } -\pi \leq \Omega \leq \pi$$

- DFT (discrete Fourier transform)

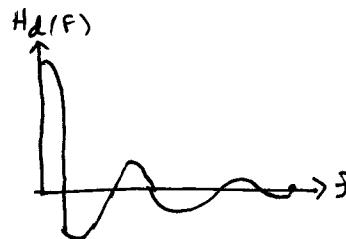
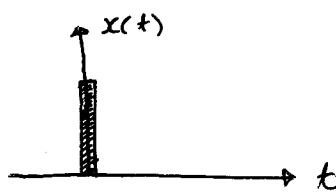
$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\left(\frac{2\pi k n}{N}\right)} ; \text{ where } \Omega = \frac{2\pi k}{N} \sim 2\pi f \left(\frac{1}{N}\right) \sim \omega$$

- ZT (z-transform)

$$X(z) = \sum_{n=0}^{N-1} x[n] z^{-n} ; \text{ where } z = e^{j\Omega} = e^{j\omega T} = e^{sT}$$

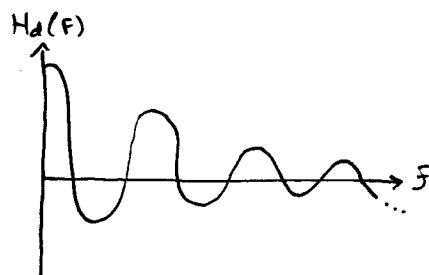
$$z = e^{sT}$$

- Input impulse



Finite number of steps

FIR: Finite impulse response filter



Infinite number of steps

IIR: Infinite impulse response filter

### 2) Design of IIR Filters

- analog filter

- digitization,  $H_d(z)$

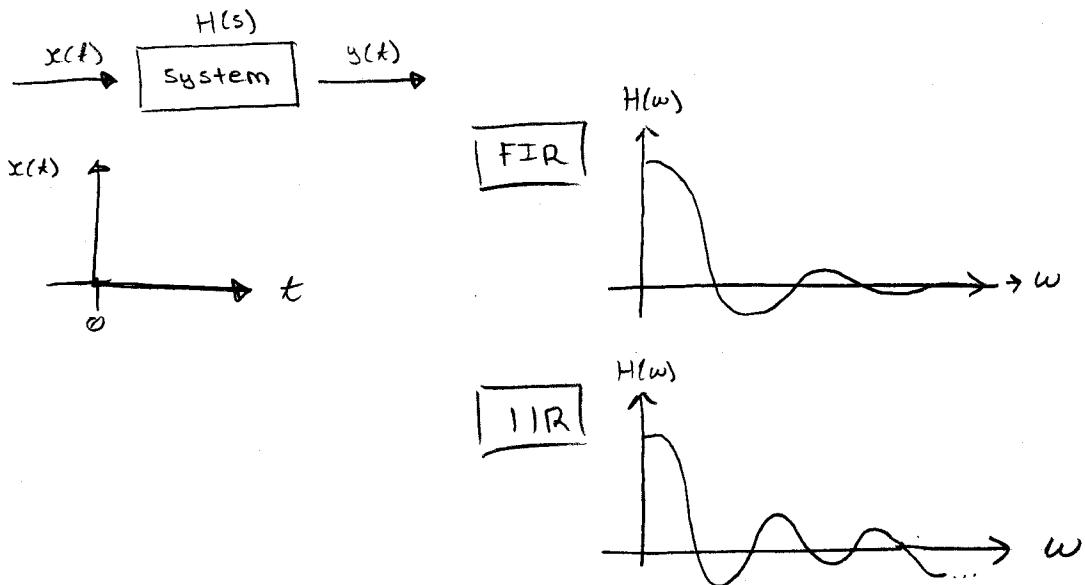
$$z = e^{sT}$$

$$\ln z = sT$$

$$s = \frac{1}{T} \ln(z)$$

(1)

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### Design of IIR Filters

- analog filter prototype  
 $H(s), H(\omega)$
- transform analog prototype  
→ digital filter :  $H_d(z)$

$$s = 1/T \ln(z)$$

$T$  = time data sample interval  $1/f_s$

$$\text{Taylor} : h_z = 2(z + z^3/3 + z^5/5 + \dots)$$

Bilinear transformation

$$s = 1/T \ln(z) \approx (\pi/\tau)(z^{-1}/z+1)$$

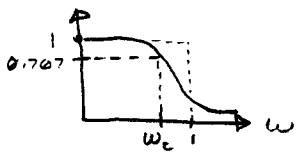
$$H_d(z) = H(z) = H\left(\frac{\pi}{\tau} \frac{z-1}{z+1}\right)$$

$$H(s) \sim h(t) \text{ (approximate)}$$

### 3) Warping Errors

$$H_d(z)$$

LPF with cutoff freq.  $\omega_c$



Digital Filter  
 $\Omega_c = \omega_c T$

$H_d(z)$  has cutoff freq.

$$\Omega_c = 2 \tan^{-1}(\omega_c T / \alpha) + \omega_c T$$

~ warping error  
approx. bilinear transformation

guy

pre-warping

$$\Omega_c = 2 \tan^{-1}(\omega_c T / 2)$$

$$\Omega_c/2 = \tan^{-1}(\omega_c T / 2)$$

$$\tan(\Omega_c/2) = (\omega_c T / 2)$$

$$w_b = (2/T) \tan(\Omega_c/2)$$

Cut-off freq. of analog prototype

$$\omega_p = (2/T) \tan(\Omega_c/2) = (2/T) \tan(\omega_c T / 2)$$

to replace  $\omega_c \rightarrow \Omega_c = \omega_c T$

Example 4.8 Consider the two-pole Butterworth

Filter with transfer function:

$$H(s) = \frac{\omega_c^2}{s^2 + \sqrt{2}\omega_c s + \omega_c^2}$$

Filter with  $\omega_c = 2$ , and  $T = 0.2$

$$\leftrightarrow f_s = 1/T = 5 \text{ Hz}$$

digital filter

$$\begin{aligned} H_d(z) &= H(s) |_{s=(2/T)(z-1/z+1)} \\ &= \frac{\omega_c^2}{((2z+1)(z-1/z+1))^2 + \sqrt{2}\omega_c ((2/T)(z-1/z+1)) + \omega_c^2} \\ &= \frac{0.0309 z^2 + 0.0605 z + 0.0309}{z^2 - 1.4514 z + 0.5724} \end{aligned}$$

$$\Omega_c = (2/T) \tan^{-1}(\omega_c T / 2) = 0.3948$$

$$\text{Desired: } \Omega_c = \omega_c T = 2 \times 0.2 = 0.4$$

$$\begin{aligned} \omega_p &= (2/T) \tan(\Omega_c/2) = (2/0.2) \tan(0.4/2) \\ &= 2.027 \text{ rad/s} \end{aligned}$$

$$\omega_p \rightarrow \omega_c \quad (\text{prewarping})$$

$$H_d = \frac{0.0309 (z^2 + 2z + 1)}{z^2 - 1.444z + 0.5682}$$

$$\Omega_c = \omega_c T = 0.4$$

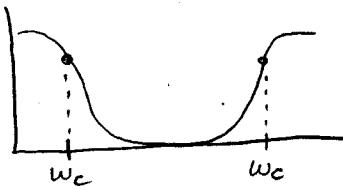
Solution

$$H_d(z) = -2$$

$$(-\pi \sim \pi)$$

## Design of IIR Filters in MATLAB

- bilinear



- butter (prototype, Freq. transformation, pre-warping)

- cheby ( $\omega_c = \omega_c T / \pi$ )

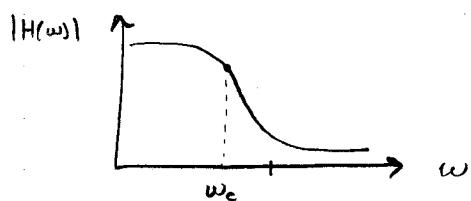
- Filter

Solution

$$x(t) = 1 + \cos t + \cos(5t)$$

$$\omega = 1$$

$$\omega = 5$$



$$1 < \omega_c < 5$$